





# **Data sheet**

# MAiRA® is the first cognitive robot.

With fully integrated novel sensors and an unprecedented integration of artificial intelligence in control systems and applications MAiRA® is leading a new era of robots. The robust and rigid design combines the performance of a high-end machine with easy programming and infinite possibilities for interaction – both for beginners and experts. MAiRA® tears down the boundaries between humans and machines and brings them closer together for good.

| General<br>Specs            | MAiRA Pro S                      | MAiRA Pro M            | MAiRA Pro L            |
|-----------------------------|----------------------------------|------------------------|------------------------|
| Payload                     | 15-18 kg                         | 12-15 kg               | 9-12 kg                |
| Reach                       | 1.100 mm                         | 1.400 mm               | 1.600 mm               |
| Degrees of Freedom          | 6 or 7 rotating joints           | 6 or 7 rotating joints | 6 or 7 rotating joints |
| Weight                      | 49.5 or 53 kg                    | 48 or 51.5 kg          | 52.5 or 56 kg          |
| Robot<br>Mounting           | Any orientation                  | Any Orientation        | Any Orientation        |
| IP classification           | IP65                             | IP65                   | IP65                   |
| Data & Power<br>Cables      | Complete inner harness and ducts | Complete inner harness | Complete inner harness |
| Footprint Base              | Ø 240mm                          | Ø 240mm                | Ø 240mm                |
| Status<br>Illumination      | RGB LED on each axis             | RGB LED on each axis   | RGB LED on each axis   |
| Tgt. Performa-<br>nce Level | Pld Cat.3 / SIL3                 | Pld Cat.3 / SIL3       | Pld Cat.3 / SIL3       |
| Tgt. Repeata-<br>bility     | Up to ± 0.01 mm                  | Up to ± 0.01 mm        | Up to ± 0.01 mm        |

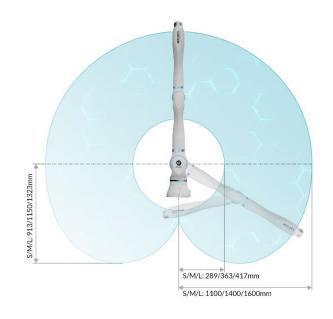
| TCP Connector Flange   |   |
|------------------------|---|
| Hole pattern           | DIN ISO 9409-1-50-7-M6  |
| Compressed Air (*opt.) | 3 x Push-Pull-Plug – 3mm<br>OD                                  |
| I/O power supply       | 24V 600mA   |
| Interfaces             | EtherCAT, GPIO, Modbus<br>via M8 8-pin-A-M   IEC<br>61076-2-104 |
|                        |   |

| 3D RGB-D Camera                   |
|-----------------------------------|
| 6-DOF F/T-Sensor in Flange        |
| Zero gravity                      |
| Touchless Safe Human<br>Detection |
| 3D Voice Recognition<br>Sensor    |
|                                   |

<sup>\*</sup> optional features are available at additional cost



| Movement |                          |               |
|----------|--------------------------|---------------|
|          | Working Range            | Working Range |
| A1       | ±360°                    | 120 °/Sec.    |
| A2       | ±120°                    | 120 °/Sec.    |
| A3       | ±270°                    | 150 °/Sec.    |
| A4       | ±150°                    | 150 °/Sec.    |
| A5       | ±270°                    | 200°/Sec.     |
| A6       | ±160°                    | 200°/Sec.     |
| A7       | ±360° / endless optional | 360°/Sec.     |



| Software & Controller |
|-----------------------|
|                       |

| Motion Controller            | Real-Time NR-Motion Master                                       |
|------------------------------|--|
| Machine Learning (ML) Kernel | Smart Applications, Performance Enhancement                      |
| Open Architecture            | 3rd Party Apps, Access to Low Level<br>Controllers & Sensor Data |
| Software Interfaces          | Robot, Sensor & AI SDKs  |
| Safety Architecture          | Safe Master & FSoE Communication                                 |
| Safety Features              | STO, SS1, SS2, SBC, SLS  |

# **Programming Features**

| Smart GUI                    | NR Easy Programming InterfaceNR-<br>Motion Master  |
|------------------------------|--|
| Fast Programming             | Shortcut Buttons, Voice Control,<br>Gesture Control (*opt.), Dynamic Path<br>and Force Recording |
| Human-Robot-<br>Interaction  | Visual-, Audio- and Force-Feed- back,<br>Face Recognition, Motion Tracking                       |
| Environment<br>Visualization | 3D CAD Data & Sensor Data  |



#### **Control Cabinet**

| Dimensions   | 598mmx540mmx236mm<br>23.5inx21.3inx9.3in  |
|--------------|---|
| Weight       | 25kg/55.1lbs  |
| Power Supply | 100-240 VAC, 50/60 Hz, 3,2 kW   |
| Interfaces   | EtherCAT, TCP/IP, Modbus<br>TCP, GPIO, UDP, OPCUA   |
| IOs          | 20 configurable safe IOs 14 digital in 8 digital out 10 digital in/out 8 analog in 8 analog out |



| Dimensions   | 285mmx228mmx95mm  |
|--------------|-------------------|
| Resolution   | 1280 x 800        |
| Display      | 10.1" touchscreen |
| Cable Length | 5m                |

## Note:

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