

Force-Sensitive Robotics

for the AI community

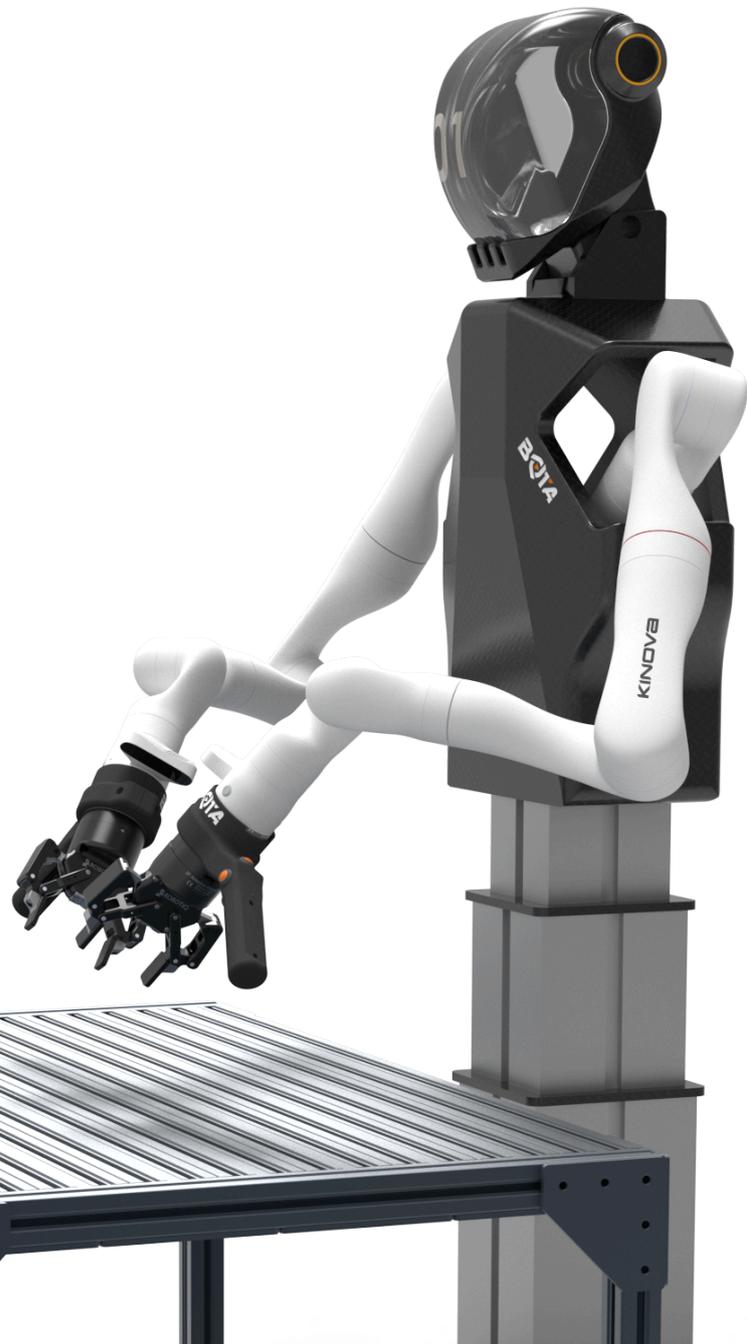
Force-sensitive robotic systems accelerate learning of Robotic Artificial Intelligence. Bota's robotic systems are based on state-of-the-art force control and hardware used in research and industrial environments. Bota offers Haptic Teleoperation and Kinesthetic Teaching with maximum efficiency and accuracy for data collection. On top of this, Bota developed TACTO, a platform that brings all together in real-time.

TACTO

Get started with

- Haptic Teleoperation
- Kinesthetic Teaching
- Full Robot State
- Force Torque Sensing
- Robust Tactile Sensing

Start now
Contact us



A platform to get started with Robotics AI – Today

- Robot state
 - Joint position, velocity & torque
 - Cartesian pose & twist
 - Wrench at TCP
 - Tactile sensing at the fingertips
- Visual Information
 - Realsense 3D camera or other
- Natural Language
 - Write your own text and store in SQL database



Teleoperation with haptic feedback



Kinesthetic Teaching with full transparency

