VISO ROBOTICS

DePalletizing Solution

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I. Introduction

I.1 Document identification

This appendix to the **OVI** user manual contains information about the **OVI depalletizing** solution. It must be read and understood by the integrators/end clients of OVI before the system is powered on for the first time.

It is mandatory to follow all instructions and guidance provided in this appendix.

I.2 Scope and Purpose

The appendix provides a general product overview and description of the design, functionality, and basic operation and instructions of **Ovi DePalletiser**.

This document is aimed at users with the following knowledge and skills:

- Basic knowledge of mechanical engineering;
- Basic knowledge of electrical and electronic systems;
- Knowledge of the Universal Robots programming concepts.

I.3 Intended use

Use is only permitted after performing a risk assessment for the complete robot system.

The complete system needs to be installed in accordance with the safety requirements specified in the standards and regulations of the country where it is installed.

Interfacing other machines is permitted only after the integrator eliminates any significant hazard that does not respect safety regulations.

NOTE:

Changing the structure of the product, e.g. by drilling holes, etc. can result in damage to the components. This is considered improper use and leads to loss of warranty.

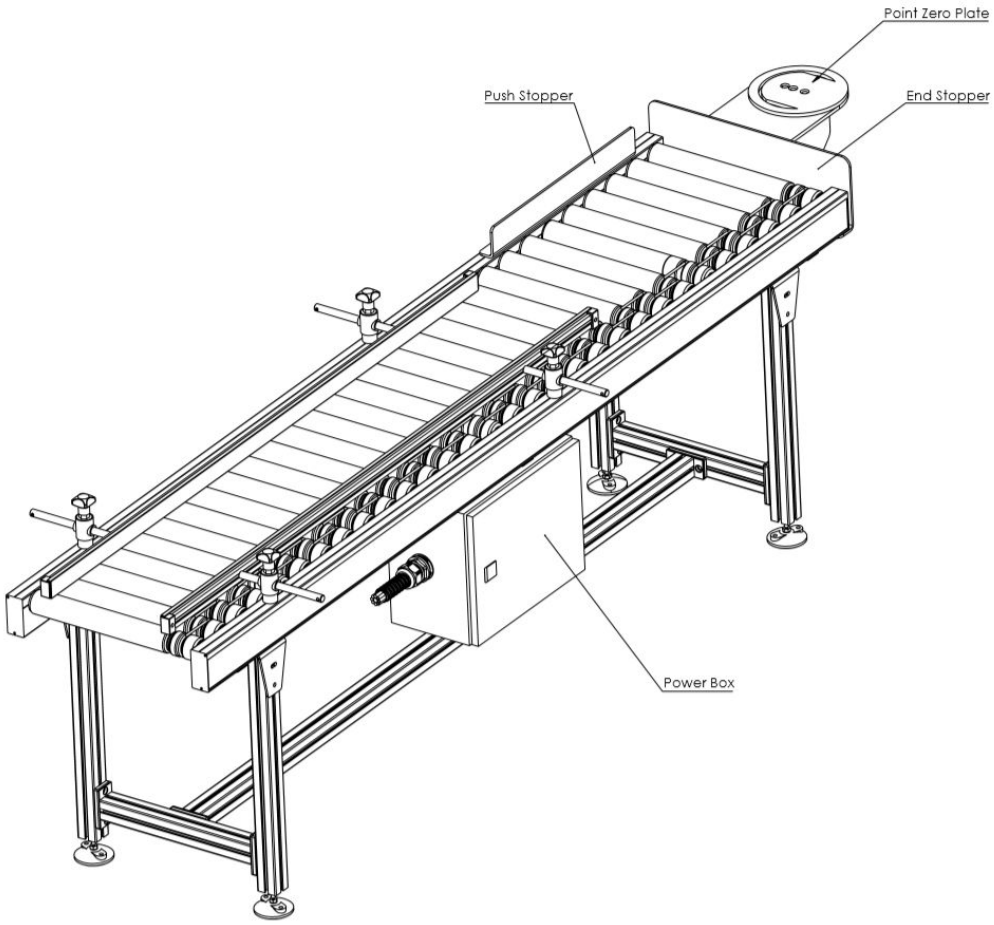
II. Feature Components

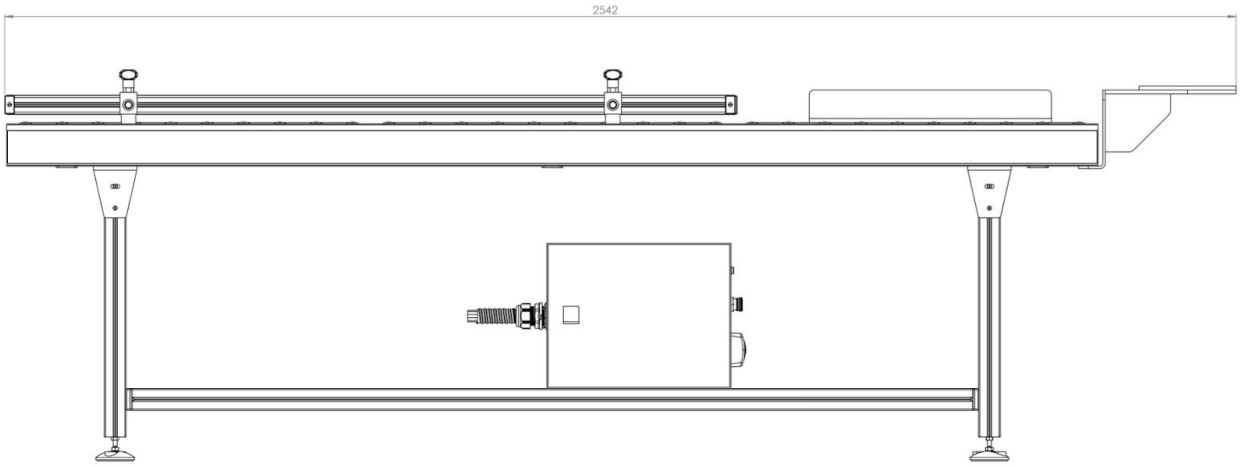
II Overview of the product

Ovi DePalletiser is a quick setup depalletizing solution that is easily integratable and allows users to define box arrangement patterns for a swift mode of depalletizing, reducing commissioning time and human error. The package includes a conveyor, vacuum gripper, Ovi Depalletiser URCap, URP, and Ovi Pattern Maker software.

II.1 Conveyor

For Ovi depalletizing solution, the conveyor is an extra option.

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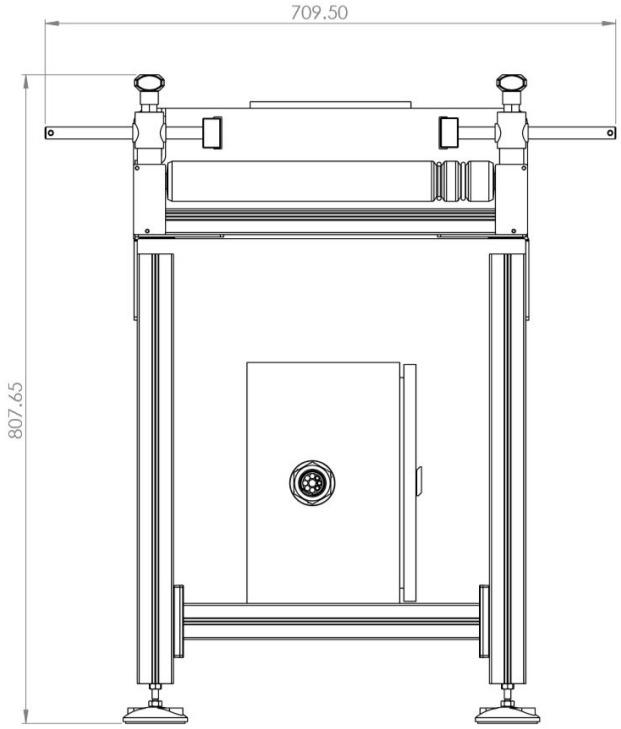
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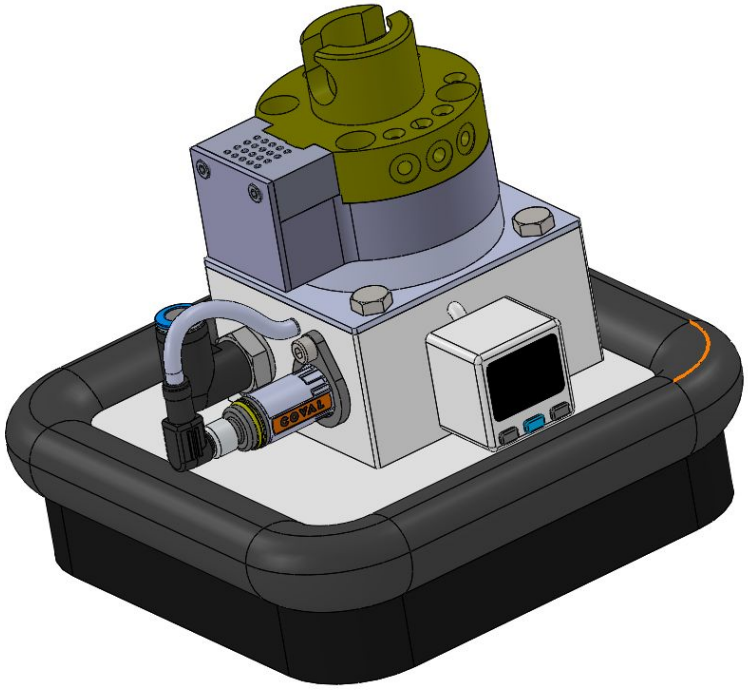
807.65

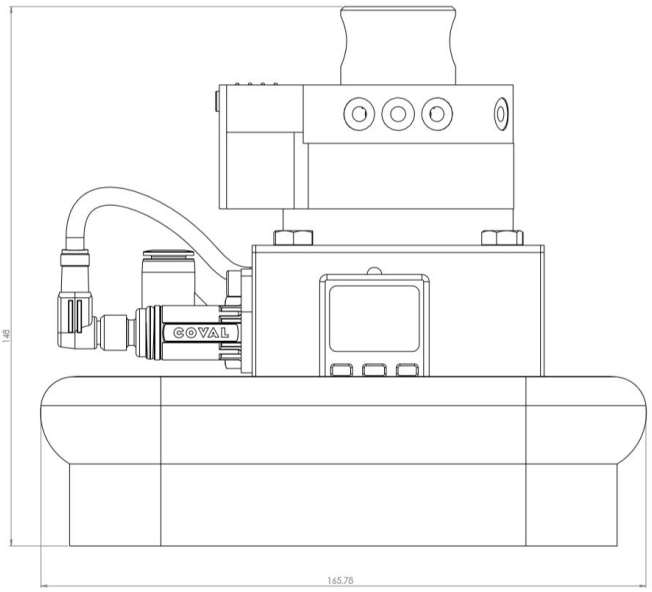
II.2 Vacuum gripper

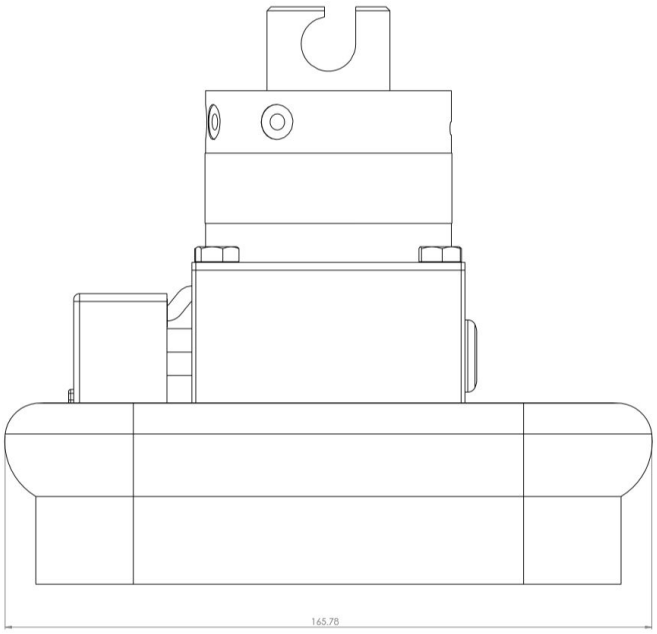
Carbon vacuum gripper with foam gripping interface, fully integrated.



Item	Value	Unit
Overall dimensions		
- **Length L**	150	[mm]
- **Width**	150	[mm]
- **Height**	148	[mm]
Air consumption	135	[l/min]
Weight	1.341	[kg]

Design Data





Technical Data

Suction rate (max.)	90	[l/min]
Air consumption	135	[l/min]
Sealing element	Foam Interface	
Weight	0.8	[kg]
Sound level	72	[dBA]

III Ovi Depalletiser URCap

The URCap contains functionalities that allow the UR10 robot arm to perform the desired depalletising procedure. It allows the user to load depalletising pattern files, transfer information stored in the pattern file to the program interface, and continually checks that the proper tool is connected before performing any depalletising action.

III.1 Software requirements

Ovi URCap

III.2 Installation

The Ovi Depalletiser URCap can be installed following the same installation procedure as any other URCap.

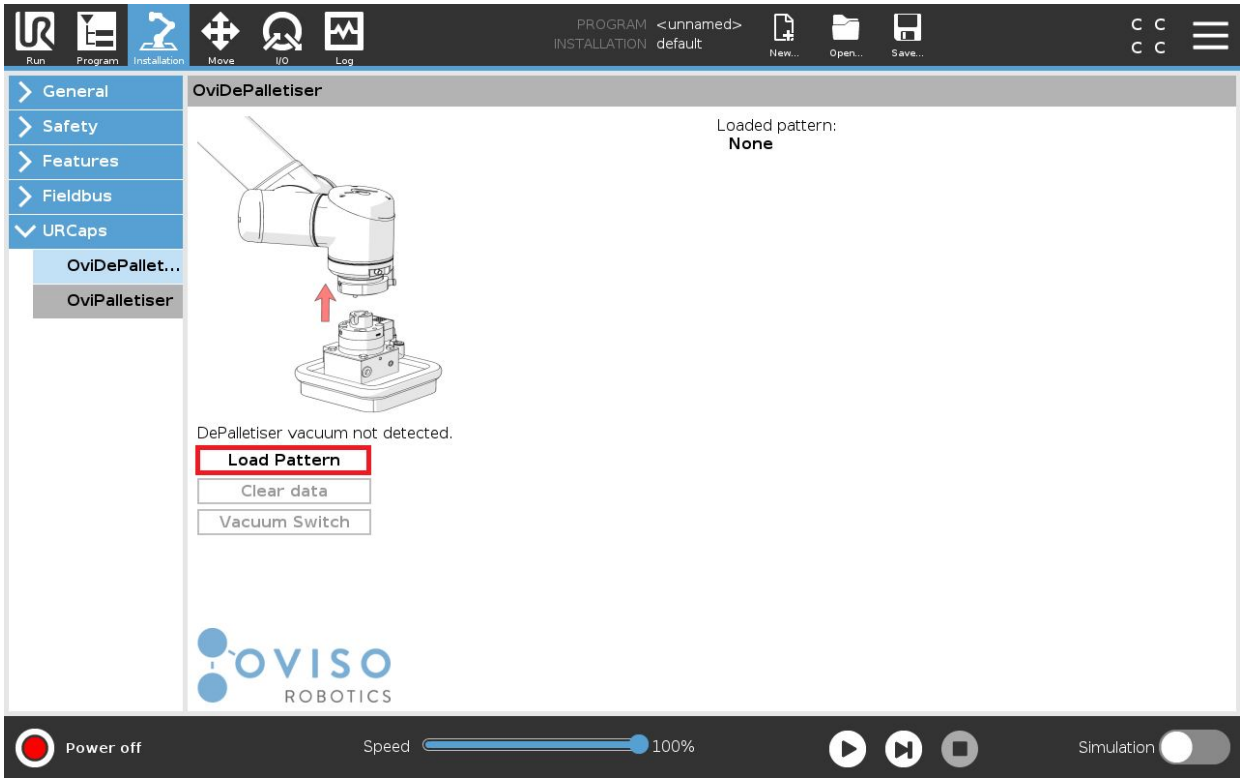
1. Navigate to the URCap setup screen: Settings -> URCaps;
2. Click the button labeled “+”;
3. Navigate to the location of the .urcap file;
4. Select the desired file;
5. Press “Open”;
6. Restart the robot to finish the installation.

III.3 Features

1. Load files containing depalletising pattern;
2. Display loaded pattern information;
3. Detection of vacuum gripper tool;
4. Turn the air pump on/off.

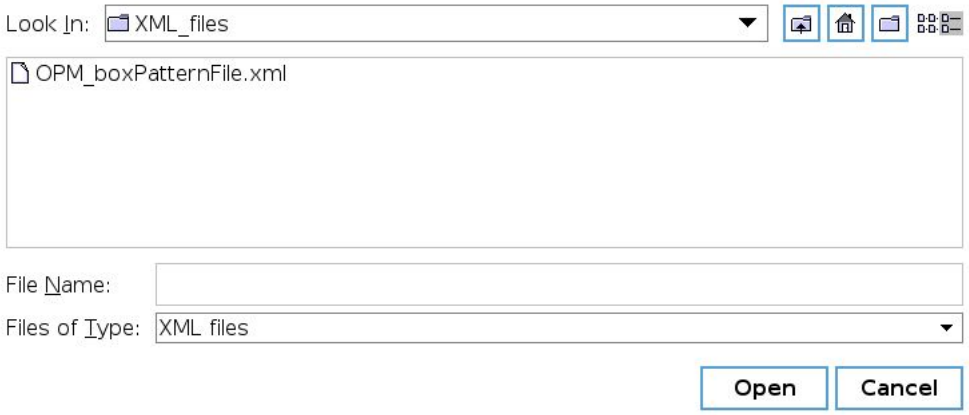
III.4 Usage

Step 1: Load pattern file



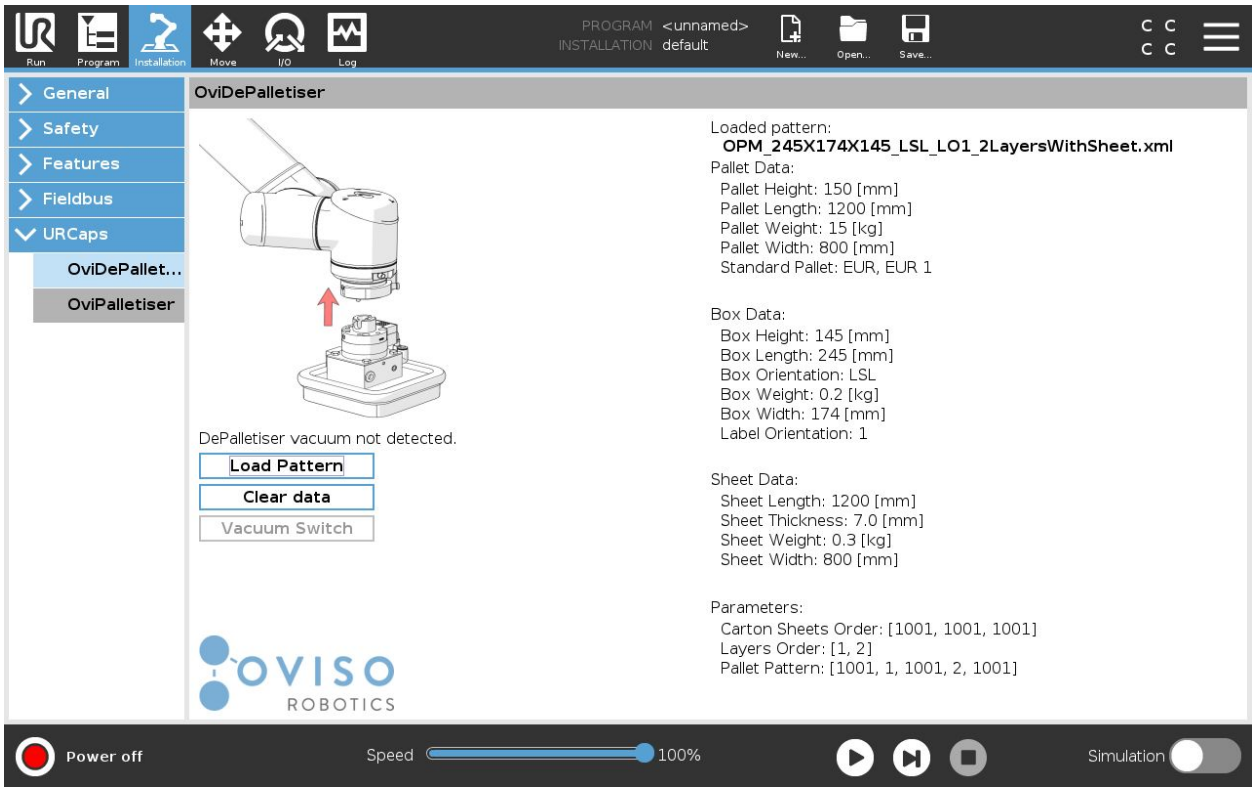
An XML file containing a depalletising pattern can be loaded by pressing the “Load Pattern” button on the left hand side of the user interface.

This will launch a window where the user can navigate to the desired pattern file.



When the file has been selected, click “Open” to load it.

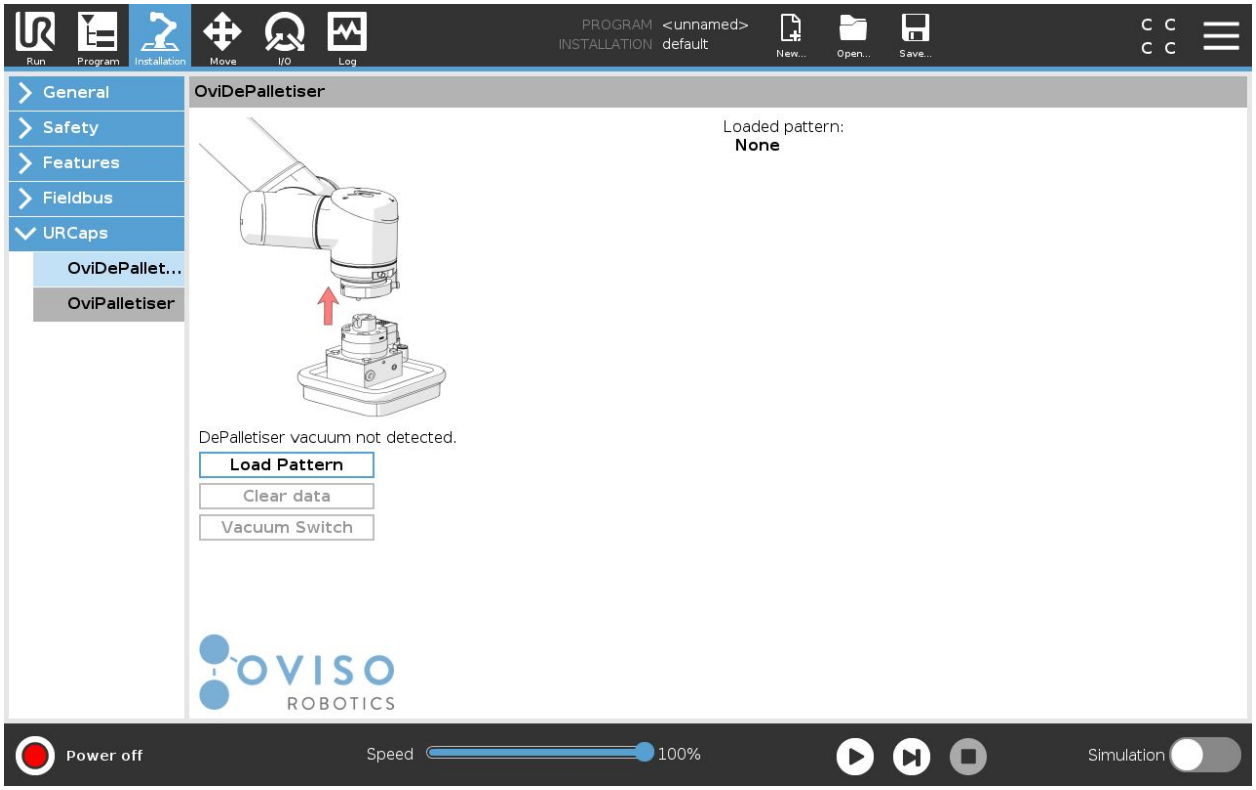
After this has been completed, the name of the selected file is displayed on the right hand side of the UI as well as the values of the parameters contained in the file.



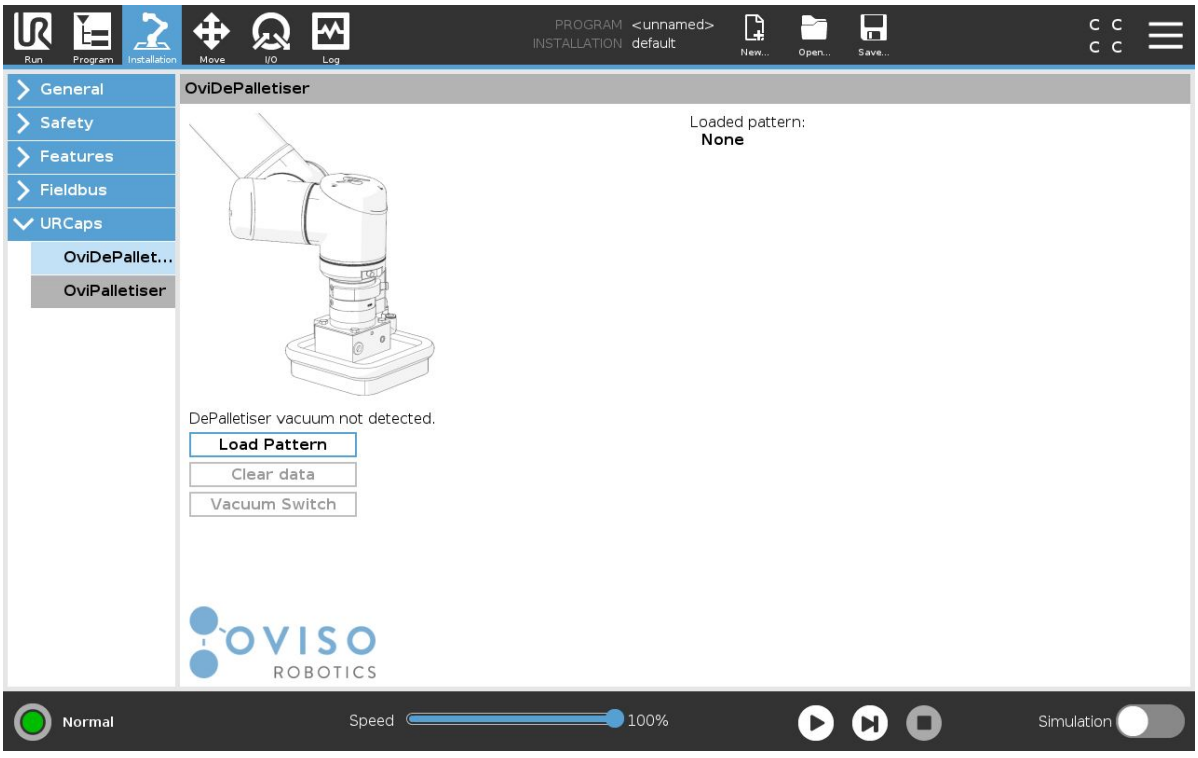
Step 2: Tool check

The image displayed on the top left of the UI indicates if the vacuum gripper tool is connected or not.

Before the vacuum gripper tool is connected:



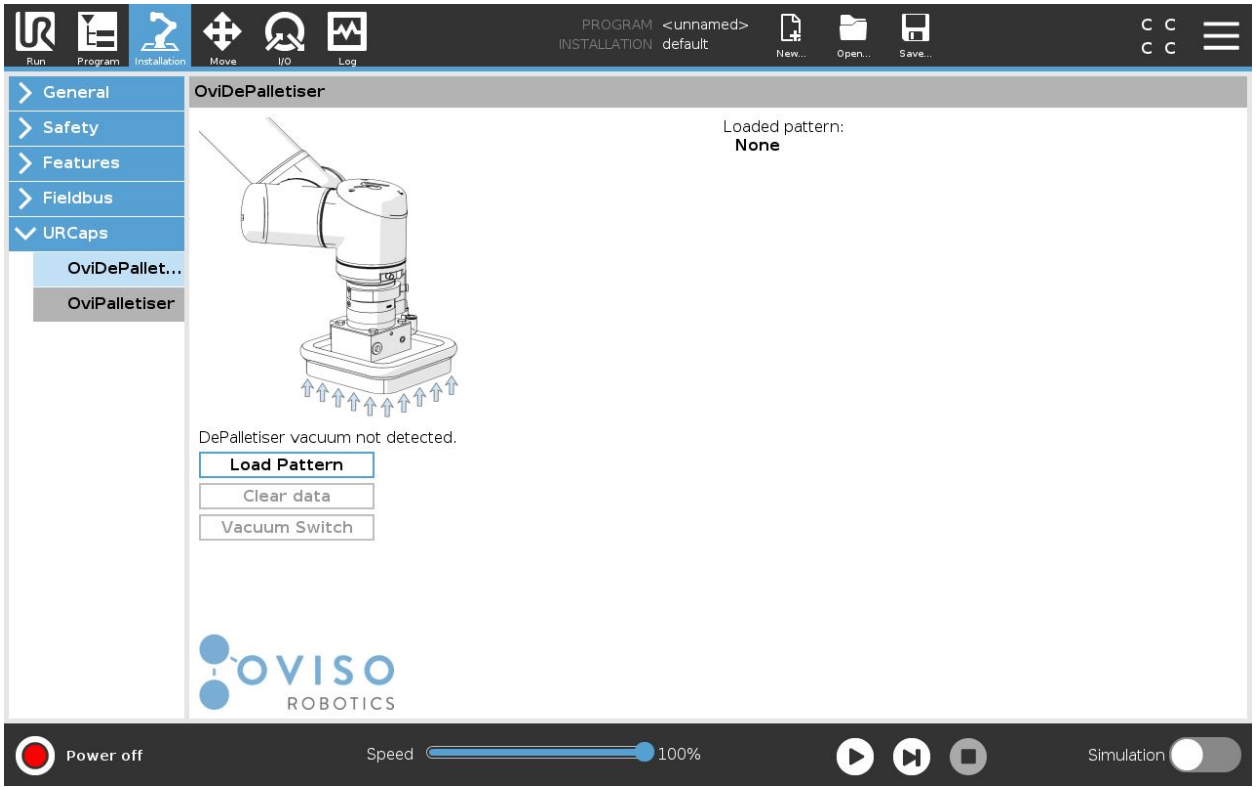
After the vacuum gripper tool is connected:



Step 3: Turn air pump on/of (optional)

While the vacuum gripper tool is connected the URCap detects its presence and enables the “Air pump” button.

This button may now be clicked in order to activate air flow to the tool, and clicked again in order to deactivate it. The top left image changes according to the status of the air flow.



IV Ovi DePalletiser URP

The Ovi DePalletiser URP makes use of the functionalities implemented by the URCap and contains the commands that move the robot to the appropriate place in order to complete the depalletizing pattern generated within the provided OPM XML file. The URP perfectly integrates the functionality of PointZero adjusting the placement of each box with respect to the last recorded PointZero coordinates.

IV.1 Software requirements

OviPalletiser URCap

IV.2 Installation

There is no installation required for this step. The user simply has to load the URP provided with the depalletising package in the Polyscope interface of the UR robot.

IV.3 Features

- PointZero: waypoints are adjusted according to PointZero coordinates allowing the robot to self-calibrate after its position has changed;
- Stop/Resume depalletizing process: if the depalletising process was interrupted, the user is able to resume the operation from the point where the interruption occurred;
- Pallet detection: The frame is fitted with presence sensor on each side which inform the operator if a pallet is present or absent;
- Signal light activation: the frame is also fitted with a signal light which signals the completion of the palletising operation to the user.

IV.4 Usage

Step 1: Load the URP by clicking “Open” in the Polyscope interface.

Step 2: Make sure that an OPM xml pattern file is loaded in the OviDePalletiser URCap view.

Step 3: Press the play button in order to start the depalletising process.

V Ovi Pattern Maker

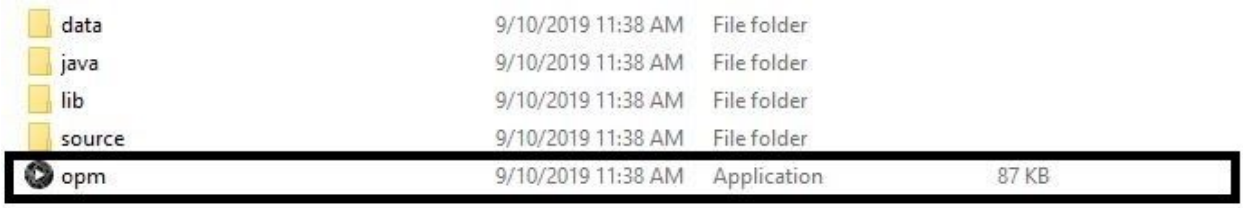
The Ovi DePalletiser package contains the Windows/Linux application Ovi Pattern Maker, which helps the integrator/client to configure the depalletizing pattern, in less than 5 minutes.

V.1 System requirements

Windows (7 or greater, x86 or x64), Linux (32 bit or 64 bit).

V.2 Installation

Ovi Pattern Maker requires no installation. To launch the application simply run the executable named “opm” IN Windows, or run navigate to the OPM folder and run “./opm” command from a terminal in Linux.



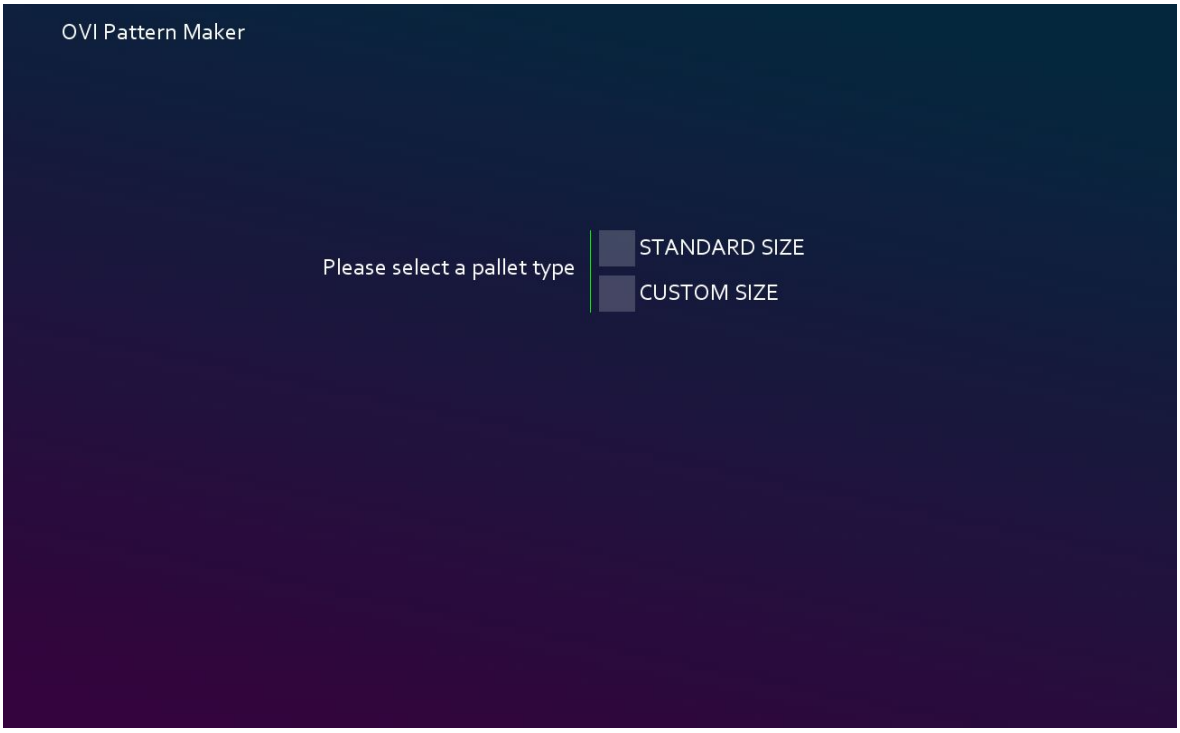
V.3 Features

The Ovi Pattern Maker features are:

1. Possibility to choose a predefined pallet size or to specify a custom pallet;
2. Specify box configuration;
3. Choose label orientation;
4. Configure the layers on a pallet, including the possibility of adding sheets;
5. Choose number of boxes on each stroke;
6. Generate an XML file of the pattern;
7. Generate a PDF report file with the pattern.

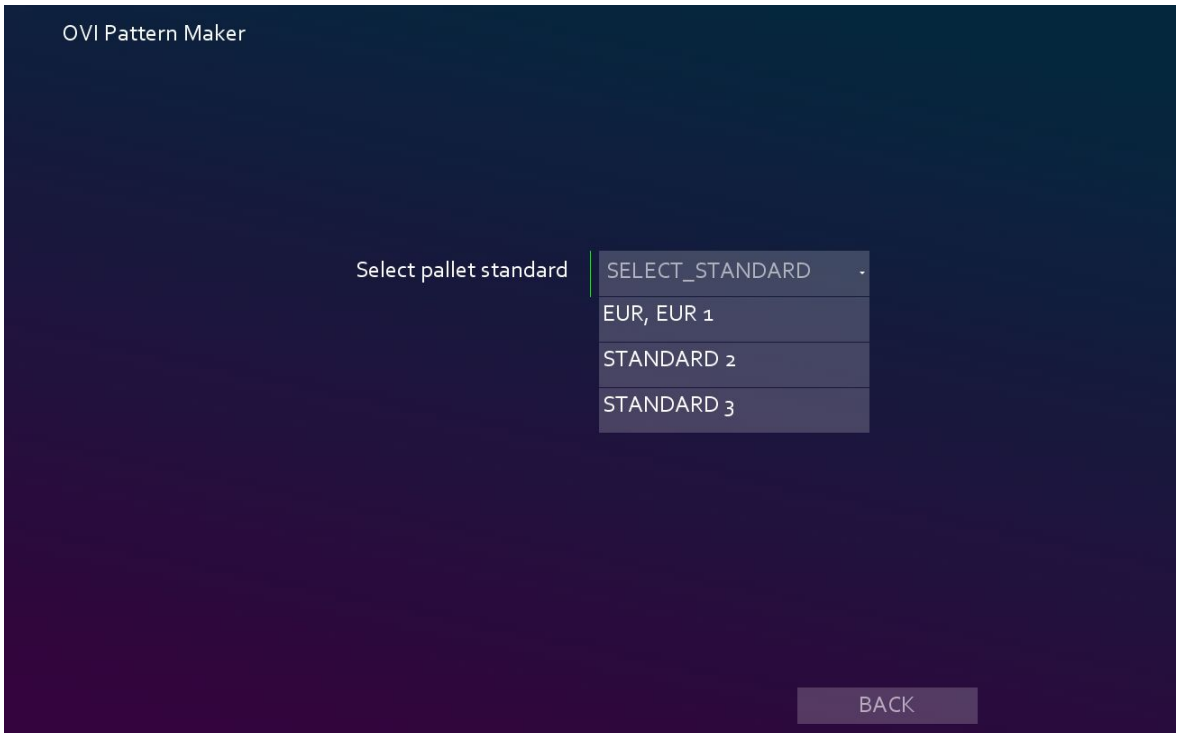
V.4 Usage

Step 1: When the Ovi Pattern Maker is launched, first of all the pallet type is chosen.

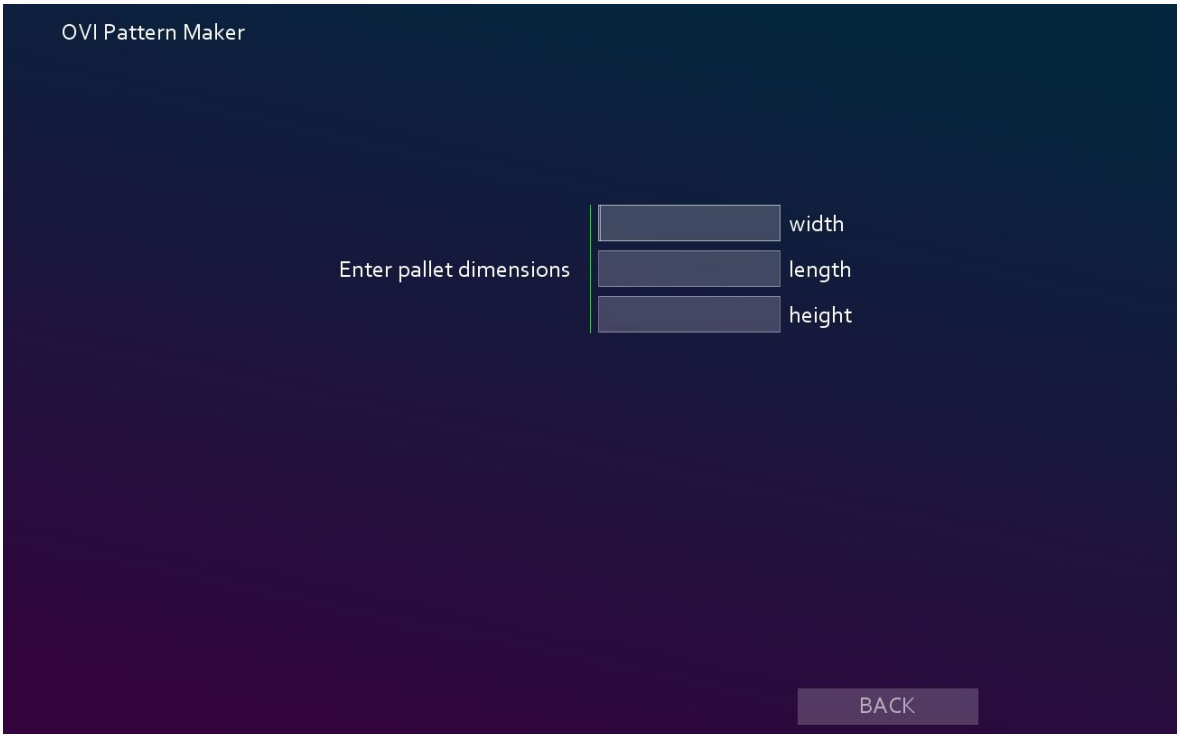


The pallet type can be STANDARD SIZE or CUSTOM SIZE. After selecting, a button labeled “NEXT” appears. Hit the button to move to the next step.

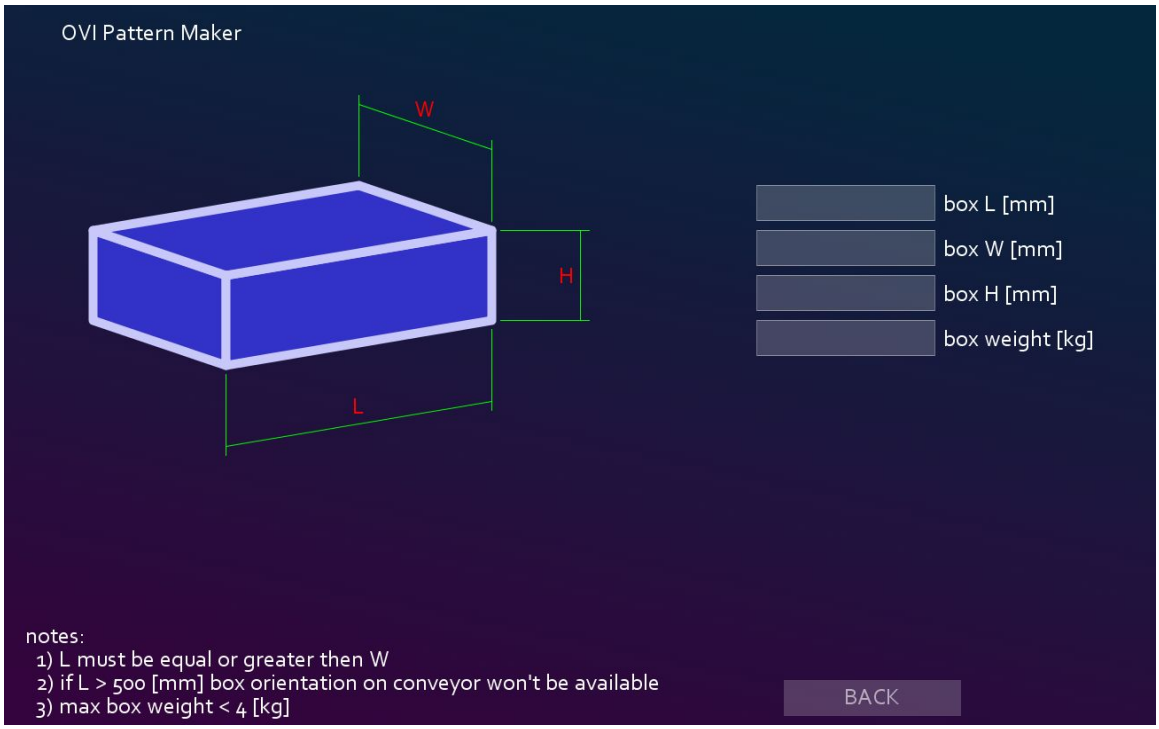
Step 2: For STANDARD SIZE a list of 6 pallet types will appear.



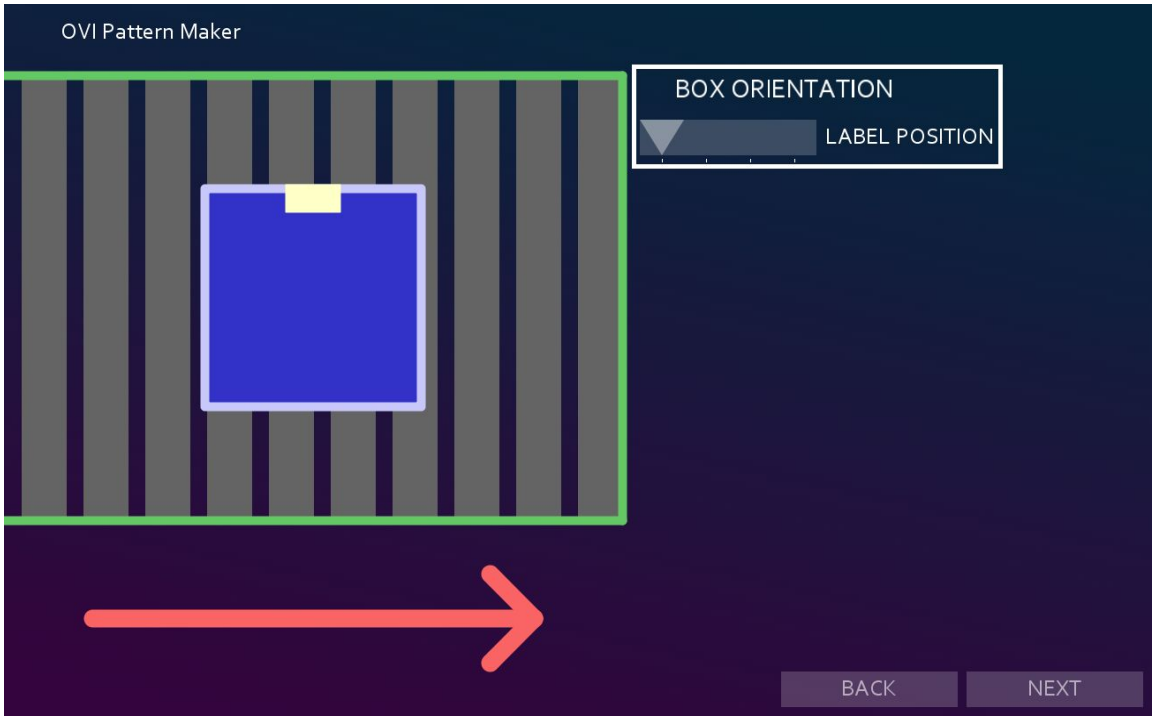
For CUSTOM SIZE the dimensions of the pallet are specified by the user. There are 3 fields which need to be filled out representing the width, length, and height of the pallet.



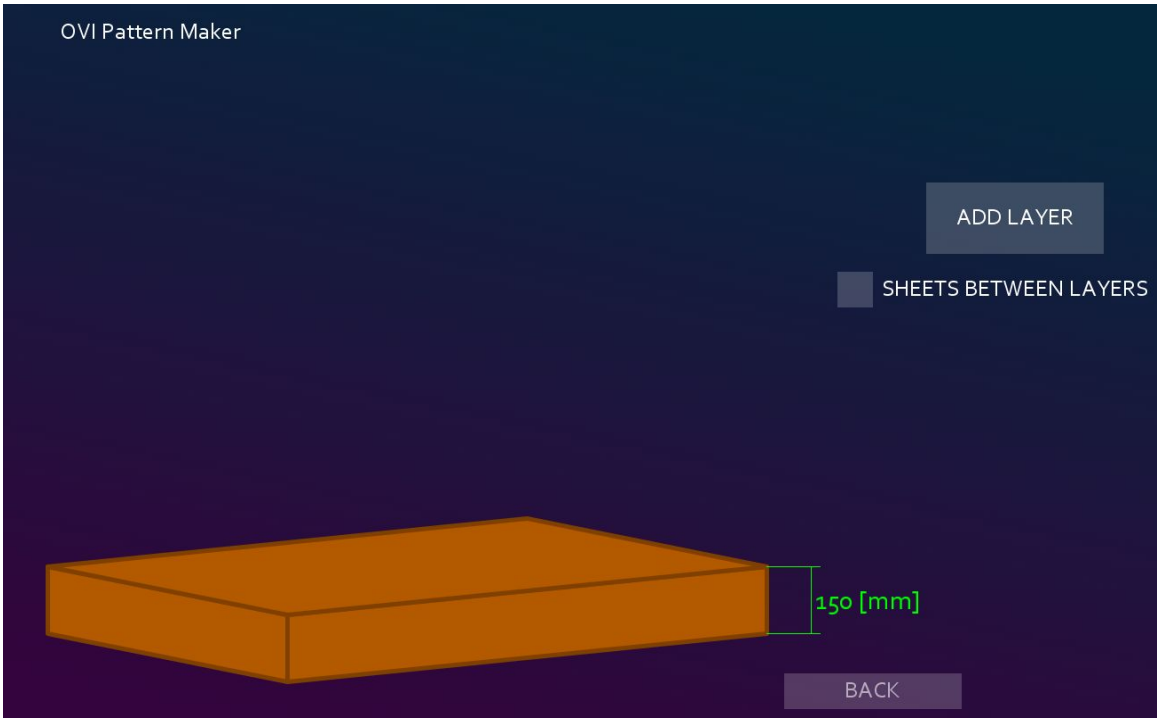
Step 3: After choosing the pallet, the next step is to configure the box by entering the length, width, height, and weight.



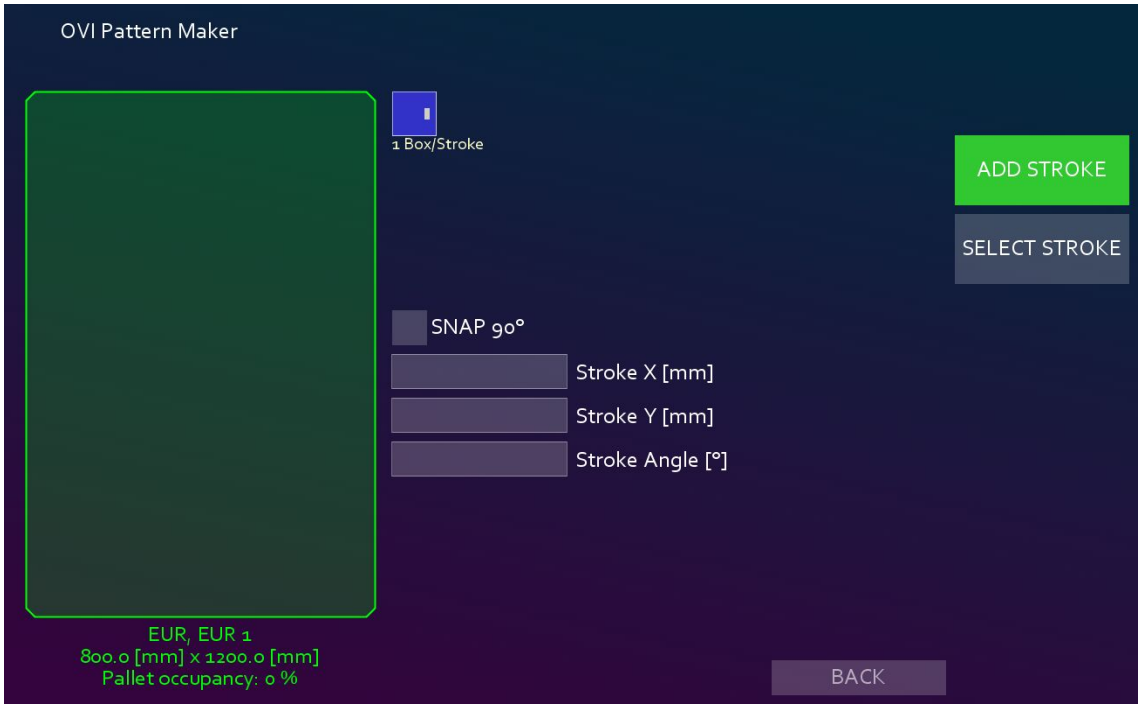
Step 4: Choose box orientation and label position.



Step 5: Configure layers and choose if sheets are added between layers.

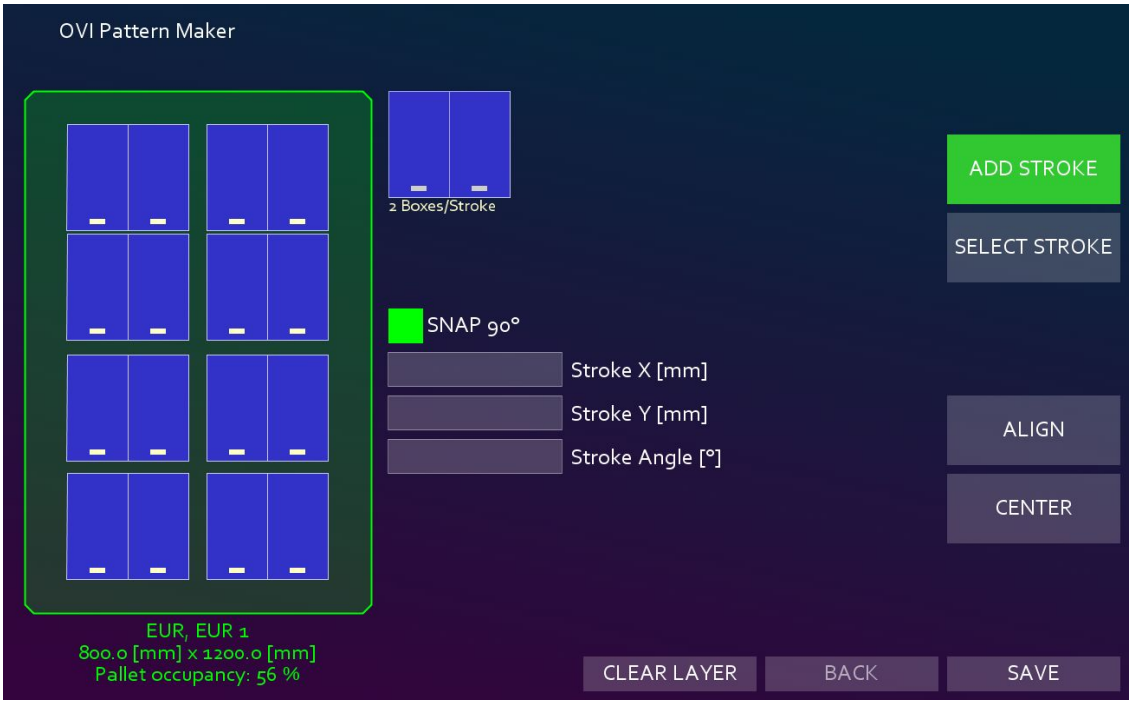


Step 6: Add the strokes on the first layer of the pallet.

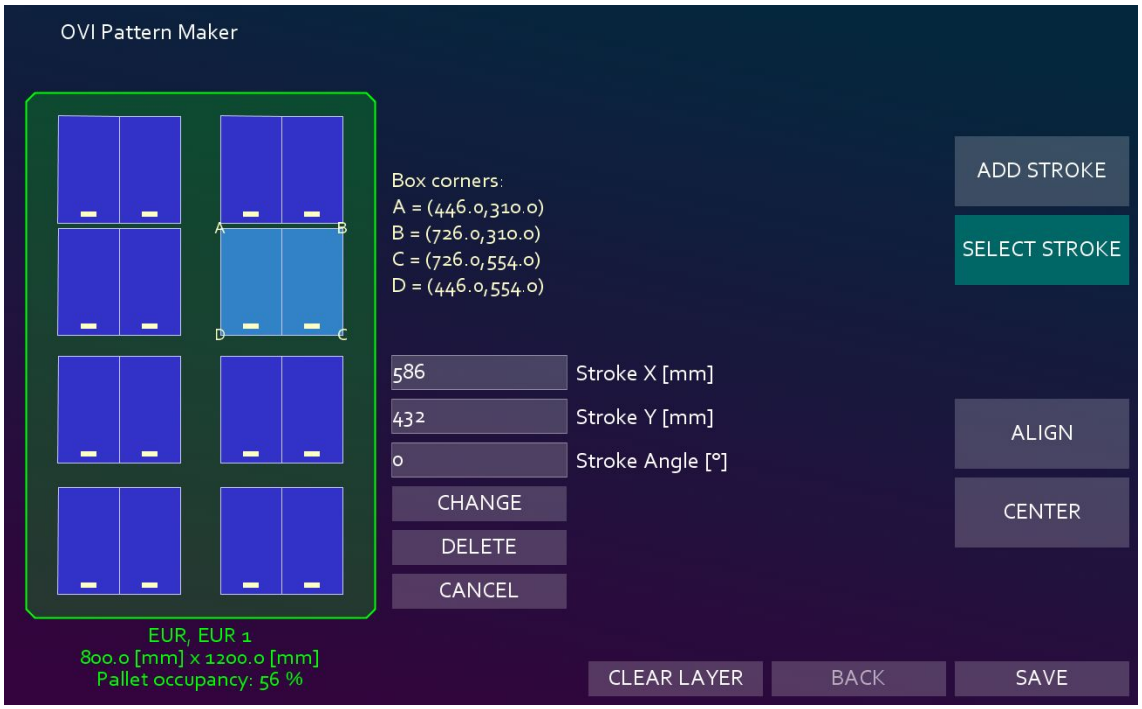


One or two boxes can be selected per stroke. Using the scroll button from mouse, the boxes can be rotated. The ”SNAP 90°” button allows the boxes to be rotated by exactly 90°.

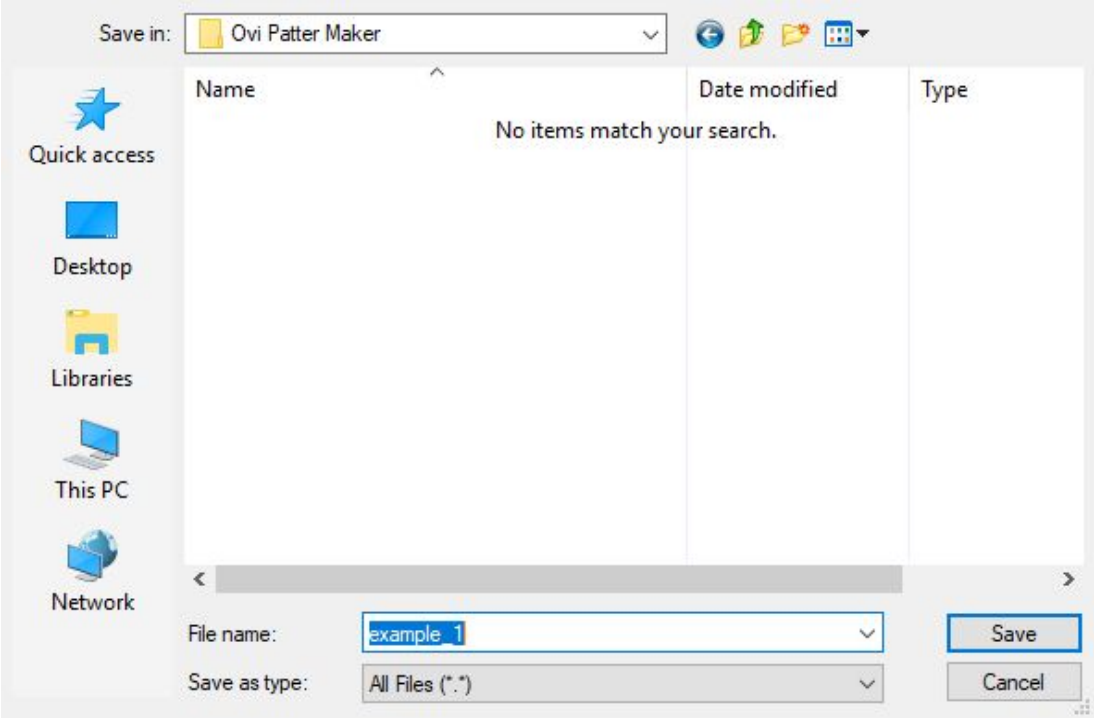
Bellow is an example of a pattern:

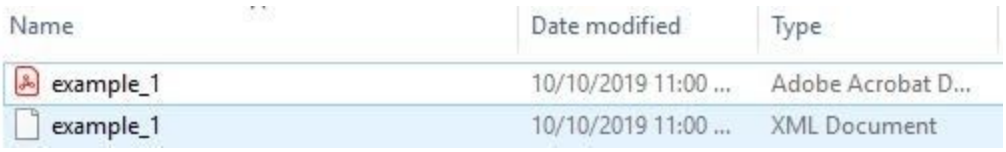


Step 7: The pattern can be edited by pressing the "SELECT STROKE" button and then clicking on an existing stroke (box or group of boxes) from the pattern on the left side.



Step 8: When everything is ready, just press "SAVE". A window will appear prompting for a name and a location where the generated files will be saved.



Step 9: Click "Save" and the Ovi Pattern Maker will generate 2 files:

a. A PDF file containing information about the pattern;
b. An XML file with relevant pattern data which should be transferred to the robot and uploaded to the Ovi Palletiser URCap.