

Safedoor

User Manual

English (original)
Version 1.1.1

Made **4**
CNC

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1 Technical Sheet SD100

Safedoor is a unique automatic door system, especially designed for robotic tending of CNC machines. The Safedoor system is also an ideal solution for CNC tending without a robot, improving operator ergonomics.

The system contains actuator(s), and a controller which together enables safe, fast and reliable operation of a CNC machine door.

With adjustable travel speed and built-in force monitoring it is capable of safe operation alongside human operators.

Features

- Easy installation, programming and risk assessment
- Optimized for integration with collaborative robots
- Fast and silent operation
- Automatic door size adjustment
- Force control optimized for safe and reliable operation
- Emergency stop input for simultaneous stop when CNC and/or robot is emergency stopped.
- Capable of handling both single and double door CNC machines
- Flexible mounting brackets for easy integration with different CNC machines

| | Minimum | Typical | Maximum | Unit |
|--------------------------|---------|---------|---------|------|
| Stroke | 100 | - | 1000 | mm |
| Installation length | 1224.5 | | 2224.5 | mm |
| | 48.2 | | 87.5 | inch |
| Adjustable Speed | 280 | 500 | 500 | mm/s |
| Open/close time @ 750 mm | | 3.1 | | s |
| Force @ 15 mm opening | | 108 | 150 | N |
| Force @ 40 mm opening | | 124 | 150 | N |
| Weight of a door | | 100 | 400 | kg |
| | | 220 | 880 | lb |

Specifications

| | |
|------------------------|---|
| IP rating, controller | IP66 |
| IP rating, actuator | IP54 |
| Digital interfaces | URCap, Universal Robots (Polyscope ≥ 3.14 or 5.9) Omron Components, TM Robots (TMFLOW ≥ 1.76.3300) 24V galvanically isolated I/Os |
| Dimensions, controller | 300 x 300 x 155 mm 11.8 x 11.8 x 6.1 inch |
| Dimensions, actuator | 1224.5 x 284 x 130 mm 48.2 x 11.2 x 5.1 inch |
| Weight, controller | 6.6 kg 14.5 lb |
| Weight, actuator | 11.2 kg 24.7 lb |

Typical applications

- CNC machine tending by collaborative robots
- CNC machine tending by operators, improving ergonomics
- Automatic operation of CNC machines with one or two doors

Operating Conditions

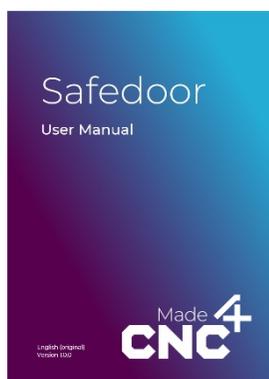
| | Min. | Typical | Max. | Unit |
|------------------------------------|--------|---------|------|-------|
| Input voltage | 90 | 230/110 | 260 | VAC |
| Input voltage frequency | 47 | 50/60 | 63 | Hz |
| External fuse | 6 | - | 16 | A |
| Operating temperature, ambient | 0 | - | 50 | °C |
| | 32 | - | 122 | °F |
| Relative humidity (non-condensing) | 10 | - | 95 | % |
| Calculated MTBF (5 min cycle) | 33,000 | | | hours |

What is in the box?

The system is composed of two packages: one with the controller and another package per actuator. Depending on the type of CNC machine, you will need a controller package and either one or two actuator packages.

The controller package contains:

- Controller cabinet with:
 - Controller board
 - Power supply (110/220VAC to 24VDC)
 - 5m power cable (N+L+PE)
- Printed instruction manual
- USB stick, containing:
 - Digital instruction manual
 - URCap for [Universal Robots](#) (PolyScope v. 3.14 / 5.9 and above)
 - Components for [Omron TM Robots](#) (TMFLOW 1.76.3300 and above)
- Operator panel with 5m cable



Each actuator package contains:

- Actuator, 1000mm, 300N, 500mm/s
- Low mounting bracket
- Tall mounting bracket
- Bag of mounting fasteners:
 - 2x M12x45 bolts
 - 2x M12 lock nuts
 - 4x M12 washers



Please check that all the parts are present and without defects before starting the installation.

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2 Quick guide



DANGER

You must read, understand, and follow all safety information in this manual, as well as the manuals for robot, CNC machine and all other associated machinery before initializing door motion. Failure to comply with safety information could result in severe injury or death.

Actuator

1. Unpack the content of the box (See full list of supplied equipment on page 6)
2. Mount the tall bracket on the machine body.
3. Mount the low bracket on the door.
4. Make sure the two brackets are aligned and separated by at least 1210mm when the door is closed.
5. Mount the actuator between the brackets and secure it in place using the provided bolts, washers and lock nuts. Use the appropriate mounting holes in the tall bracket to ensure the actuator is leveled.
6. Tighten the bolts and ensure that the actuator is firmly seated in the brackets, unable to rotate axially in either end.
7. Route the actuator cable to the controller, through the cable gland and connect the motor cables to controller boards J4 / J5.
8. If installing two actuators, repeat the process for the second actuator on the second door.

See full description and other mounting options in the section *Mechanical integration* on page 12.



INFO

The actuator must be able to fully reach the doors mechanical end stops in both directions. Therefore, the actuator cannot be fully retracted when the door is closed. The minimum spacing of 1210mm between the brackets must be respected.

Controller

1. Mount the controller in a suitable location, typically close the CNCs control cabinet.
2. Connect the actuator cable to the controller PCB connector J4.
3. If installing two actuators, install the second actuators to J5.
4. Connect the CNC Not Active input from CNC Machine to the controller PCB connector J6.
5. If required, connect the outputs of an emergency stop circuit to J9.
6. If required, connect the operator open/close button panel to J8.
7. Connect the output signals in J3 to inputs on the robot.

8. Connect the input signals in J1 to outputs on the robot.
9. Connect "CNC Door Closed" to the CNC machines cycle start input.

For full list and description of inputs and outputs, see *IO functional description* page 18.

Operator panel

1. Mount the operator panel on a flat surface where it is convenient for the operator to reach.
2. Route the cable from the panel to the controller cabinet.
3. Connect the button wires from the cable to J8 pins 1 and 2 on the Controller Board.
4. Connect power supply +24V to the cable and GND to J8 pin 3 (common).

See description in Button panel input group J8 on page 19.

Configuration

1. Jog the connected doors to fully opened position using the Jog buttons on the Controller Board. Press "Config/Reset" to exit manual mode.
2. Press and hold "Config / Clear" on the Controller Board for 3 seconds to initiate the configuration cycle.
3. Observe the doors and ensure that both doors move all the way to the fully closed position.
4. Observe that the two green LEDs on the controller board light up, indicating that the configuration cycle was completed successfully.
5. Use the robot inputs (J1) or the button panel (J8) to open and close the door a few times, to allow the controller to adjust to the width of the door(s).

See full description in *Configuration* on page 22.



INFO

The controller checks if the CNC is active before it attempts to open the doors. Ensure that the CNC Not Active signal is provided.

For more guides and instruction videos, visit www.made4cnc.com



3 Mechanical integration

It is important to plan the mounting process carefully before starting the work. This section guides you through the decisions in the process.

Mounting configuration

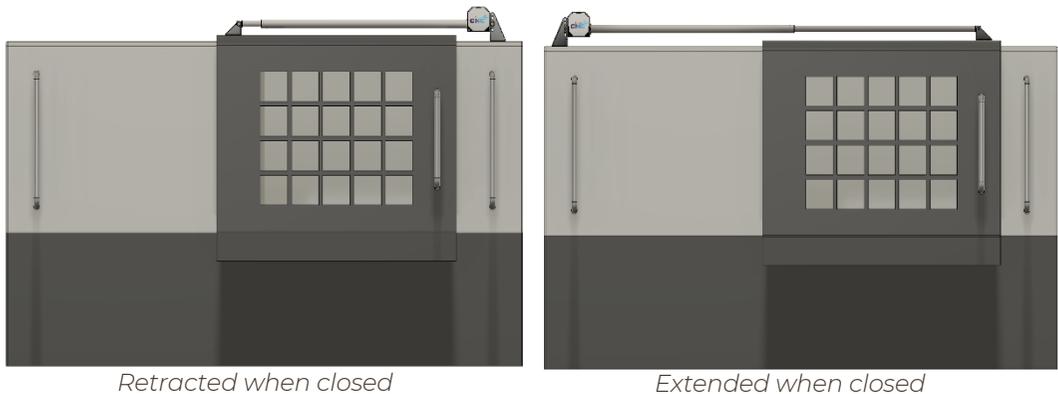
To accommodate various CNC machine designs, the Safedoor actuator and accompanying brackets offer a variety of different mounting options.

The two mounting brackets share similar mounting hole patterns and can both be used to fixate either end of the actuator.

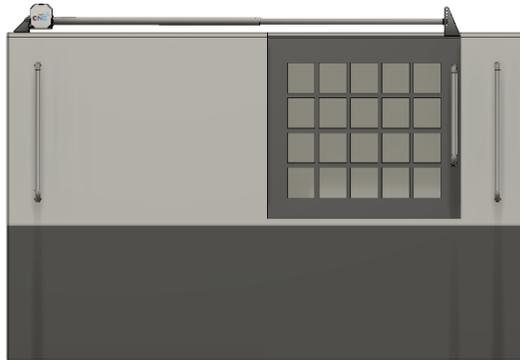
The low bracket is intended to be mounted on the highest of the two mounting points on the machine, and the tall bracket should be mounted on the lower mounting point. The tall bracket has multiple mounting positions for the actuator, allowing adjustment of the height to ensure the actuator is level with the door's direction of motion.

The end of the actuator with the motor-cabinet should always be mounted on the stationary side, i.e., on the CNC machine body. The rod end of the actuator should be mounted on the door of the CNC machine.

The actuator(s) can be mounted such that it is retracted when the door is closed and extended when the door is open – or extended when the door is closed and retracted when the door is open. Keep in mind that the wires in the motor connector J4 (J5 for secondary door) must be swapped when using the extended when closed option.



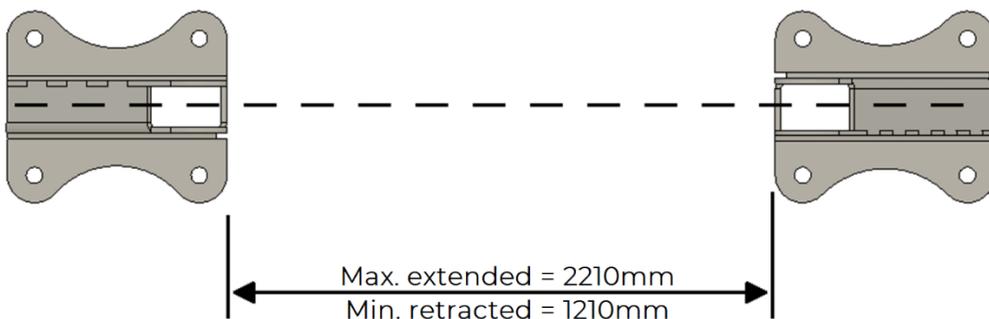
When the door is internal or the mounting point on the door, for other reasons, is lower than the body of the CNC machine, the tall bracket should be mounted on the door, to allow the actuator to remain parallel with the doors line of motion.



Internal door mounting.

Mounting the brackets

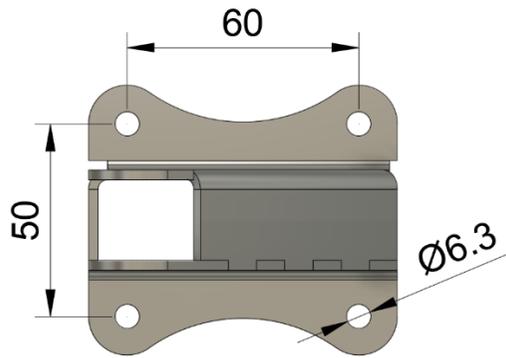
When determining the position of the mounting brackets, it is important to ensure that they are lined up correctly and that the distance between them is correct. When the two mounting brackets are closest together, there must be 1210mm between them to ensure proper operation of the actuator. The actuator will, when fully extended, push the brackets up to 2210mm apart.



Maximum and minimum bracket distances over the travel length of the door.

The movement of the door must be mechanically limited so that the maximum and minimum distances are observed. If the mechanical stops provided by the CNC machine is not able to provide such stops, additional stops must be installed.

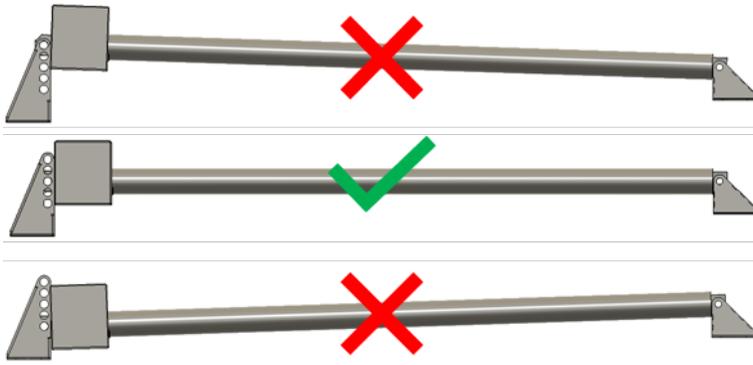
Once the positioning of the two mounting brackets have been determined, they can be mounted on the CNC machine body and door. The brackets should be mounted using the four mounting holes provided on each bracket.



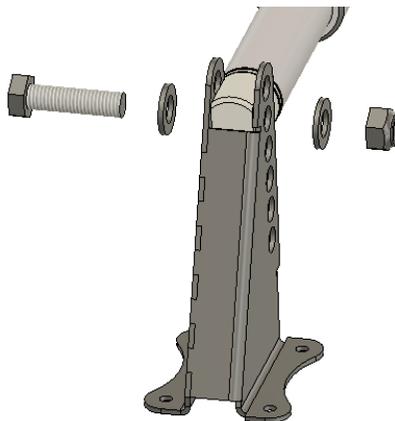
Dimensions in mm.

Mounting the actuator

The tall mounting bracket is made with several sets of mounting holes to allow height adjustment during the installation. Use the correct set of holes to adjust the actuator to a horizontally aligned position.



Each end of the actuator should be bolted into the brackets using the provided M12x45 bolts, M12 washers and M12 safety nuts. See the figure below. The bolts must be tightened firmly, and the actuator should not be able to jiggle axially when correctly mounted.



Safedoor actuators must only be installed to work with axial pushing and pulling forces. Lateral and radial loading is not permitted.

The actuators must be mounted in the supplied mounting brackets using the supplied bolts, tensioned to the specified torque, to ensure that neither of the actuator's ends are able to rotate in the mounting bracket. The minimum distance between the mounting brackets must be respected, as the actuator cannot withstand retracting beyond this distance.



DANGER

Loose bolts can cause the actuator to fall from the CNC door. Always make sure that bolts are firmly tightened.

The actuator can come apart, fall and/or take damage if the driven beyond its specified length. Always ensure that the minimum and maximum distance between brackets is complied with.

Mechanical stops must be provided by the CNC machine or installed by separately the integrator, to ensure the minimum distance is kept. The Safedoor system uses the mechanical stops to automatically detect the width of the door and thereby scheduling proper acceleration and deceleration of the door prior to closure of the door. This ensures that the majority of the kinetic energy of the door is removed before the door closes, further reducing the severity of pinching and crushing hazards.

Do not connect the actuator's power cables before verifying that it is mechanically secured and unable to rotate axially in either of the attachment points.

Maintenance and repair

All maintenance and repairs must be performed in compliance with this manual and latest service manual, which can be found on www.made4cnc.com/support.

Repairs must be performed by authorized system integrations or made4CNC. Original spare parts must be used.

Actuators and controllers are marked with a product generation number. Only combine actuators and controllers with same generation number. Ask technical support for generation details.

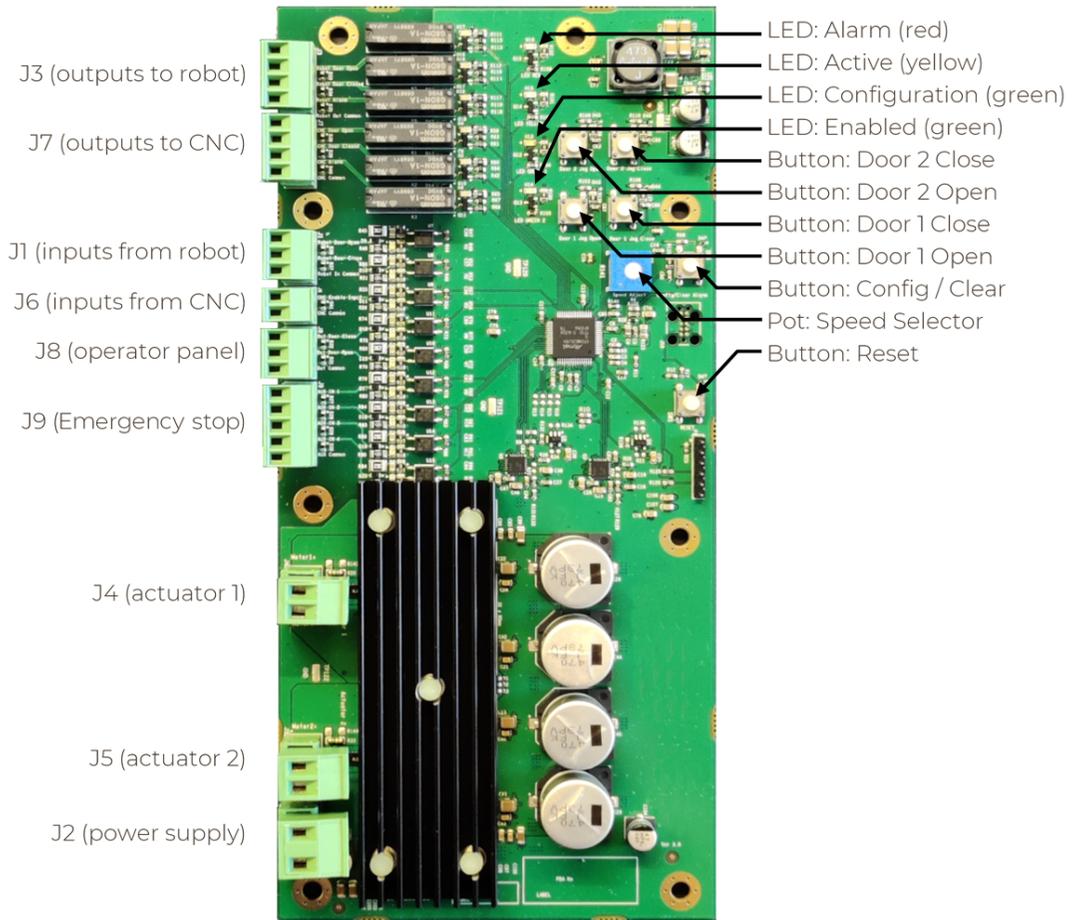


WARNING

Combining actuators and controllers from different generations can change properties of the product significantly. Safety features might not be fully functional, which can result in injuries.

Use of non-original spare parts can change the safety features significantly. This can result in unacceptable impact forces and/or reduced product lifespan, which can result in injuries.

4 Electrical connections



PCB controls

| Name | Function |
|---------------------------|---|
| Button "Door 1 open" | Press and hold to open door 1. |
| Button "Door 1 close" | Press and hold to close door 1. |
| Button "Door 2 open" | Press and hold to open door 2. |
| Button "Door 2 close" | Press and hold to close door 2. |
| Button "Config / clear" | Press to clear alarms and to exit manual mode. Hold for 3 seconds to initiate configuration cycle. |
| Button "Reset" | Press to perform a hardware reset of the controller PCB. |
| Trim pot "Speed selector" | Determines the speed mode to be configured. See <i>Speed settings</i> on page 21. |

IO connections

| Connection | Name | Signal type | Reference | Rating |
|------------|-------------------|----------------|-----------|---------------------------------------|
| J3 pin 1 | Robot door opened | Digital output | J3 pin 4 | 24V _{dc} / 1A _{dc} |
| J3 pin 2 | Robot door closed | Digital output | J3 pin 4 | 24V _{dc} / 1A _{dc} |
| J3 pin 3 | Robot alarm | Digital output | J3 pin 4 | 24V _{dc} / 1A _{dc} |
| J3 pin 4 | Robot 24V | Group common | | |
| J7 pin 1 | CNC door opened | Digital output | J7 pin 4 | 24V _{dc} / 1A _{dc} |
| J7 pin 2 | CNC door closed | Digital output | J7 pin 4 | 24V _{dc} / 1A _{dc} |
| J7 pin 3 | CNC alarm | Digital output | J7 pin 4 | 24V _{dc} / 1A _{dc} |
| J7 pin 4 | CNC 24V | Group common | | |
| J1 pin 1 | Robot open door | Digital input | J1 pin 3 | 24V _{dc} |
| J1 pin 2 | Robot close door | Digital input | J1 pin 3 | 24V _{dc} |
| J1 pin 3 | Robot GND | Group common | J1 pin 3 | |
| J6 pin 1 | CNC Not Active | Digital input | J6 pin 2 | 24V _{dc} |
| J6 pin 2 | CNC GND | Group common | | |
| J8 pin 1 | Button door close | Digital input | J8 pin 3 | 24V _{dc} |
| J8 pin 2 | Button door open | Digital input | J8 pin 3 | 24V _{dc} |
| J8 pin 3 | GND | Group common | | |
| J9 pin 1 | Emergency stop 1 | Digital input | J9 pin 5 | 24V _{dc} |
| J9 pin 2 | Emergency stop 2 | Digital input | J9 pin 5 | 24V _{dc} |
| J9 pin 3 | - | Digital input | J9 pin 5 | 24V _{dc} |
| J9 pin 4 | - | Digital input | J9 pin 5 | 24V _{dc} |
| J9 pin 5 | GND | Group common | | |
| J4 pin 1 | Actuator 1 pos | 24V power | | 24V _{dc} / 12A _{dc} |
| J4 pin 2 | Actuator 1 neg | 24V power | | 24V _{dc} / 12A _{dc} |
| J5 pin 1 | Actuator 2 pos | 24V power | | 24V _{dc} / 12A _{dc} |
| J5 pin 2 | Actuator 2 neg | 24V power | | 24V _{dc} / 12A _{dc} |
| J2 pin 1 | 24V supply | 24V power | | 24V _{dc} / 21A _{dc} |
| J2 pin 2 | GND | 24V power | | 24V _{dc} / 21A _{dc} |

Each connector group is galvanically isolated from the rest of the controller board and from each other and implemented in compliance with IEC-61131-2 Type 3.

All digital outputs are normally opened relays. When activated the output is electrically connected to the respective reference pin.

All digital inputs are optocoupled and activates when a voltage of 24V with respect to the group common ground is applied.

IO functional description

Robot output group J3

The connector group J3 are used to signal the state of the door to the robot. It should be powered by connecting the robot 24V power to J3 pin 4.

| Pin | Description |
|--------------------------|---|
| Pin 1: Robot door opened | Relay contactor is closed when the door is fully opened. This signal can be used to signal the robot that it can enter the CNC machine. |
| Pin 2: Robot door closed | Relay contactor is closed when the door is fully closed. |
| Pin3: Robot alarm | Relay contactor is closed when the system is in an alarm state. |
| Pin4: Robot 24V | Common supply for the J3 group. Relays in this group close circuits to this pin when active. |

CNC output group J7

The connector group J7 are used to signal the state of the door to the CNC machine. It should be powered by connecting the CNC 24V power to J7 pin 4.

| Pin | Description |
|------------------------|--|
| Pin 1: CNC door opened | Relay contactor is closed when the door is fully opened. |
| Pin 2: CNC door closed | Relay contactor is closed when the door is fully closed. This signal can be used to indicate to the CNC machine that it can start a new machining cycle. |
| Pin 3: CNC alarm | Relay contactor is closed when the system is in an alarm state. |
| Pin 4: CNC 24V | Common supply for the J3 group. Relays in this group close circuits to this pin when active. |

Robot input group J1

The connector group J1 are used to signal the door to open and close from the robot. Signals should be 24V when activated and 0V when not activated, with reference to J1 pin 3.

| Pin | Description |
|-------------------------|--|
| Pin 1: Robot open door | Request door open. Note that the CNC Not Active signal on J6 pin 1 must be high for door opening to be initiated. |
| Pin 2: Robot close door | Request door close. This signal should be activated by the robot when it has completed its work in the CNC machine and has moved outside of the machine and clear of the door. |
| Pin 3: Robot 24V | Common GND for the J1 group. Signals in this group are activated when 24V with respect to this pin is presented on the inputs. |

CNC input group J6

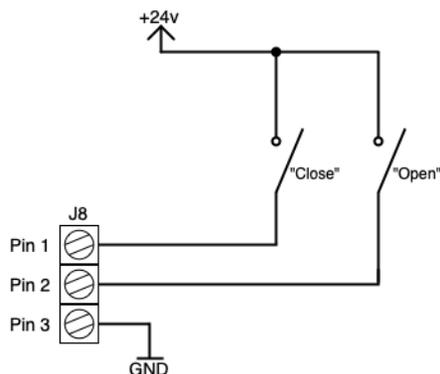
The connectors in group J6 are used to signal the door that it can safely open, as the CNC machine is not active and have unlocked the door.

| Pin | Description |
|-----------------------|---|
| Pin 1: CNC Not Active | Should be activated by the CNC machine when the machining cycle has finished and any door locks have been unlocked. The door will not attempt to open the door if this signal is not set. |
| Pin 2: CNC GND | Common GND for the J6 group. Signals in this group are activated when 24V with respect to this pin is presented on the inputs. |

Button panel input group J8

The connectors in group J8 are used to connect an external button panel, allowing manual operation of the door.

| Pin | Description |
|--------------------------|--|
| Pin 1: Button close door | Should be connected to the button for manually closing the door. When activated, the door will close. |
| Pin 2: Button open door | Should be connected to the button for manually opening the door. When activated, the door will open. |
| Pin 3: GND | Common GND for the J8 group. Signals in this group are activated when 24V with respect to this pin is presented on the inputs. |



Emergency stop input group J9

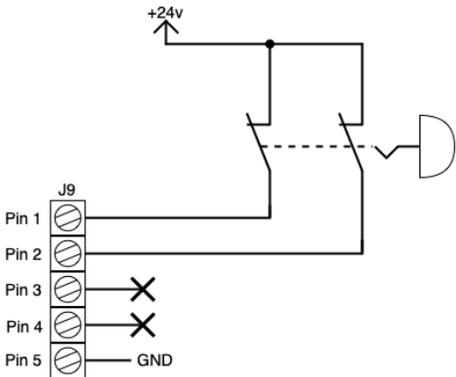
Emergency stop is only supported for controllers produced after 1/1 2022.

The connectors in group J9 comprise an emergency stop input which can be used to immediately stop door motion when CNC machine, robot and/or a separate button is put into emergency stop.

The emergency stop input is an optional feature as its use and requirements depends on the specific CNC application (See CNC manual, robot manual and risk assessment). The emergency stop input feature is automatically detected during configuration. If unused, leave the J9 terminals unconnected.

To restart motion after an emergency stop, first un-emergency stop (Both 24V signals are reestablished) and secondly provide a motion start signal from CNC machine and/or robot (All edge changes on signals from CNC and robot represents a reset to the emergency stop mode)

| Pin | Description |
|-------------------------|--|
| Pin 1: Emergency stop 1 | Can be connected to an independent output on an Emergency stop circuit. When activated (24V is removed), the system will be set in an emergency stop mode, immediately stopping door motion. |
| Pin 2: Emergency stop 2 | Can be connected to an independent output on an Emergency stop circuit. When activated (24V is removed), the system will be set in an Emergency stop mode, immediately stopping door motion. |
| Pin 3: - | Pin 3 is unused. Leave unconnected. |
| Pin 4: - | Pin 4 is unused. Leave unconnected. |
| Pin 5: GND | Common GND for the J9 group. Signals in this group are activated when 24V with respect to this pin is presented on the inputs. |



Actuator 1 connector J4

Connectors for powering the first door actuator. Note that the polarity should be inverted (i.e. the wires should be swapped), when the actuator is mounted in the extended when closed configuration.

Actuator 2 connector J5

Connectors for powering the second door actuator. See description for *Actuator 1 group J4* above.

Supply connector J2

Connector to power supply unit, providing power for the controller board and the attached actuators.



CAUTION

Pay attention to polarity when connecting signals and power to the controller board. Reversal of voltages may cause permanent damage to controller board, power-supply and any attached equipment.

Speed settings

To allow the integrator to select the appropriate traversal speed for the installation, The Safedoor controller has three different speed settings. The speed is selected by turning the speed selector (see overview on page 16). The speed setting must be set prior to running a configuration cycle, as it is latched during the configuration. Changing the speed setting has no effect before a new configuration cycle is performed.

| Setting | Description |
|---|---|
|  | High speed: 500 mm/s The potentiometer is turned fully clockwise until meeting resistance. |
|  | Medium speed: 390 mm/s The potentiometer is in center position, between the high- and low speed positions. |
|  | Low speed: 280 mm/s The potentiometer is turned fully counterclockwise until meeting resistance. |

See page 16 for selector placement.

Manual operation (jogging)

During installation it can be beneficial to be able to drive the linear actuators manually. This can be done using the buttons on the controller PCB. When either

of the buttons are pressed, the controller board enters Manual Operation Mode, and any action requested from the digital inputs are blocked until Manual Operation Mode is cancelled by pressing “Config / Clear”.

| Button | Description |
|------------------|--|
| Door 1 Jog Open | Press and hold to slowly move door 1 in opening direction. |
| Door 1 Jog Close | Press and hold to slowly move door 1 in closing direction. |
| Door 2 Jog Open | Press and hold to slowly move door 2 in opening direction. |
| Door 2 Jog Close | Press and hold to slowly move door 2 in closing direction. |

See page 16 for button placements.

Note that the “CNC Not Active” input must be set high to allow any motion.

Configuration

A configuration cycle must be performed on each actuator after it has been installed. The cycle measures the width, resistance, weight and other parameters on each door and stores it internally on the controller board. This data is later used to ensure proper speed ramping as well as high force detection, once the system is in service. When configuring with an emergency stop circuit, having high signals on J9 will activate the emergency stop feature. If no signals are high, the emergency stop feature will not be activated (*See Interfacing with an emergency stop circuit on page 26*).

To perform a configuration, follow these steps carefully:

1. Ensure that the CNC door can move freely
 - a. Linear rails must be clean, free from chips/dust/debris and well lubricated
2. Ensure that the actuator is mounted correctly on the CNC machine
 - a. The mounting brackets must be firmly mounted on the CNC machine
 - b. The actuator must be level with the machine and door
 - c. All bolts must be properly tensioned
 - d. All electrical connections must be firmly tightened
3. Ensure that the CNC machine is not operating, and that the “CNC Not Active” signal is provided and high
4. If required, ensure that the emergency stop circuit is properly connected
 - a. Ensure that emergency stop inputs receive a constant high signal
5. Ensure that power and PE (protective earth) is connected
 - a. AC power (110V or 220V) source must be connected to the power supply in the controller cabinet.
 - b. The power supply and the controller cabinet must be connected to PE (protective earth)
 - c. 24V supply and GND cables must be mounted between the power supply and the controller board
6. Press and hold “Open door 1” to jog door 1 to the fully opened position.

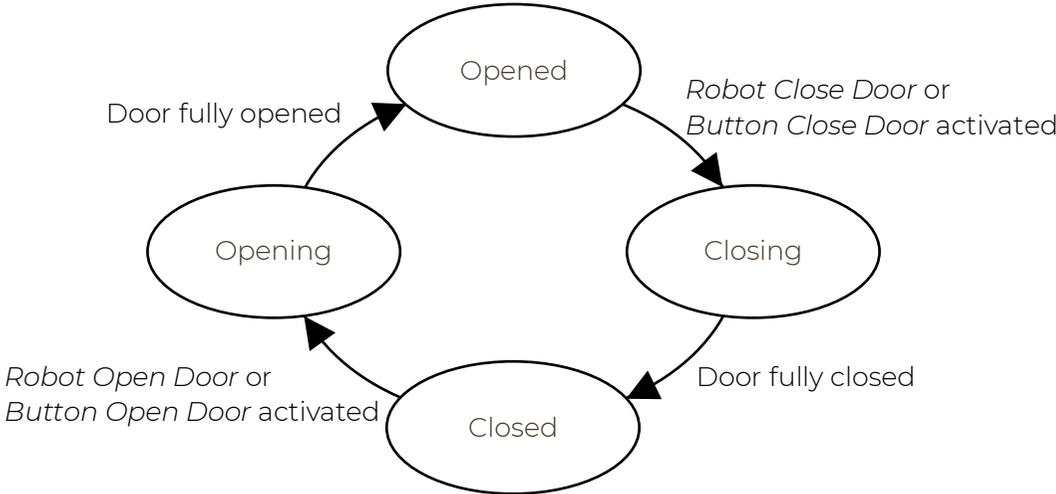
7. If a second door is installed, press and hold “Open door 2” to jog door 2 to the fully opened position.
8. Press and hold “Config / Clear” for 3 seconds to initiate the configuration cycle.
 - a. Observe the doors and ensure that both doors move all the way to the fully closed position.
 - b. Observe that the two green LEDs on the controller board light up, indicating that the configuration cycle was completed successfully.
9. Use the robot inputs (J1) or the button panel (J8) to open and close the door a few times, to allow the controller to adjust to the width of the door(s).
10. If an emergency stop circuit is connected, test to see if it stops the motion of the doors as intended.

5 Software specification

Operating states

The software on the Controller Board performs motion control and force monitoring of the actuators and communicate with the CNC machine, robot, operator panel and other equipment through digital inputs and outputs.

During normal operation, the Safedoor Controller has four operating states; Opening, Opened, Closing and Closed.



When the Controller is in *Opened* state the outputs *CNC Door Opened* and *Robot Door Opened* are activated. In this state the Controller waits for either *Robot Open Door* or *Button Open Door* to be set while *CNC Not Active* is also set. The Controller then clears the outputs and transitions to the *Closing* state,

When in *Closing* state, the door is accelerated to the configured maximum speed. The speed is maintained until the door approaches the fully closed position. Then it is slowed down and closed safely. Once the controller senses that the door is fully closed it transitions into *Closed* state and sets the outputs *CNC Door Closed* and *Robot Door Closed* active.

In the *Closed* state, the controller awaits *Robot Close Door* or *Button Close Door* to be set while *CNC Not Active* is also set. When these signals are provided, the Controller clears the *CNC Door Closed* and *Robot Door Closed* signals and transitions into *Opening* state.

When in *Opening* state, the door is accelerated to the configured maximum speed. The speed is maintained until the door approaches the fully opened position. Then it is slowed down and reaches the fully opened position safely. Once the controller senses that the door is fully opened it transitions into *Opened* state and sets the outputs *CNC Door Opened* and *Robot Door Opened*.

Note that the Controller will not respond to the inputs signals as described above if:

- 1) The controller is in Manual Mode after using the Jogging buttons. When done jogging, press Config / Clear to return to normal operation.
- 2) The controller is not configured or is currently running a configuration cycle. See *Configuration* on page 22.
- 3) An alarm has occurred. Once the cause of the alarm has been identified and rectified, the alarm can be cleared by pressing Config / Clear. See *Alarm LED (red)* on page 25.

LEDs

The Controller Board has four LEDs, indicating the state of the Controller. Below is a description of each of the LED's; please refer to the Controller Board overview on page 16 for placement of the LEDs.

Alarm LED (red)

The Alarm LED is off during normal operation. If a problem, which requires the operator's intervention, is detected the Controller switches to the *Alarm State* and the *Alarm LED* will flash one of the patterns below, to indicate the cause. The *Alarm* state is retained until the cause of the alarm is removed and the *Reset / Config* button is pressed.

| Blink pattern | Cause | Description |
|---------------|--------------------------|---|
| Solid on | Manual mode | Either of the Jog buttons was pressed and the Controller Board is in Manual Mode. |
| Single flash | Temperature Alarm | The motor driver's temperature exceeded 60C. Make sure the rails are clean and the door can move without excessive resistance. |
| Two flashes | Motion Timeout | The door didn't finish a opening or closing motion within reasonable time. Check motor wire connections to ensure the actuator is properly connected. |
| Three flashes | Force Limit | The Controller Board registered a increased force during door motion. Check for chips and other blockages of the door. Ensure the linear rails are clean and well lubricated. |
| Four flashes | Motor driver malfunction | Various internal errors; drive voltage too high, tension too low, driver malfunction or overheating. Contact your supplier for more information. |

Active LED (yellow)

The Active LED is on when the system is currently opening or closing the door. The LED is also on if a configuration cycle is being performed or if the door is being jogged manually.

Configuration LED (green)

The configuration LED is ON when the system has been properly configured. If not, it will flash to indicate that configuration is required before the system can be used.

Enable LED (green)

The *Enable LED* is on, when the *CNC Not Active* input is on, and the system can move the door.

Interfacing with CNC machines

When interfacing with the CNC machine, the system needs to be aware of the CNC's operating state, i.e. if the CNC is currently running a cycle and the doors need to remain closed, or if the cycle is completed and the door can be opened. This information should be given by setting the *CNC Not Active* signal high when the CNC is not operating, and the door can be opened. When the machine starts a cycle, it should clear this signal and remain cleared till the cycle is complete and the mechanical locks on the door have been unlocked.

The *CNC Door Opened* and *CNC Door Closed* signals can be used to signal the CNC to e.g. start a new cycle when the doors have been closed.

Interfacing with robots

The robot interface, composed of J1 and J3, allows the robot to determine the current state of the CNC machine, as well as initiating door motion. When the door opens, *Robot Door Opened* is set and the robot can start its part replacement cycle. When done, it can use the *Robot Close Door* signal the door to close. When the door is fully closed, the *CNC Door Closed* signal is set, which can be used to trigger Cycle Start on the CNC.

Interfacing with an emergency stop circuit

Optionally an emergency stop circuit can be connected to J9. This can be used to immediately stop door motion when CNC machine, robot and/or a separate button is put into emergency stop. In the emergency stop mode the system will prevent any motion of the door.

The presence of an external emergency stop circuit is captured during the configuration cycle (See *Configuration on page 22*). If either of the inputs "J9 pin 1" or "J9 pin 2" are high during the configuration, the system will register that an external emergency stop circuit is connected and will expect said circuit to be connected during operation. When neither of the signals are active (24V not present) during configuration, emergency stop mode is deactivated and the system will ignore the inputs during operation.

When configured with an external emergency stop circuit present, the system will monitor the emergency stop inputs during operation. Only when both signals are high will the system allow motion of the doors.

It is important to verify that the configuration captured the presence of an external emergency stop circuit, prior to placing the system into service. This can be done by activating the emergency stop while the door is in motion and verifying that it stops immediately.



Once the external emergency stop is deactivated and both inputs go high, the system exits emergency stop mode and proceeds to normal operation. Door motion will not start automatically when exiting emergency stop mode, even if a signal to move (robot/button open/close door) is high; a transition from low to high on one of these inputs are needed to reinitiate motion.

URCap

The Safedoor URCap enables easy and reliable setup and operation, when using Safedoor in conjunction with a Universal Robots collaborative robot. After the Safedoor system is installed and configured (see *Quick guide* on page 10), follow these steps to install and configure the URCap on a Universal Robots robot.

Installation

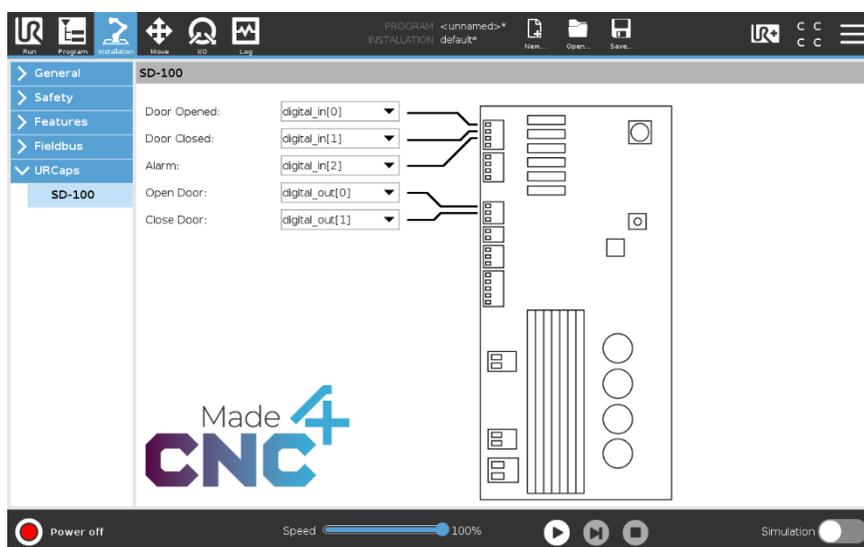
Install the URCap by inserting the provided USB stick into the USB port on the robot teach pendant. Follow these steps to install the URCap on the robot system:

1. Main menu → Setup Robot → URCaps
2. Press “+”
3. Select “USB” → “Safedoor.urcap”
4. Press “Open”
5. Press “Restart”

Polyscope will now restart and load the installed URCap.

Installation screen

The installation screen contains settings related to the installation of the Safedoor system. It can be found by navigating to *Installation* → *URCaps* → *Safedoor*. Make sure all inputs and outputs are configured to represent the actual wiring.



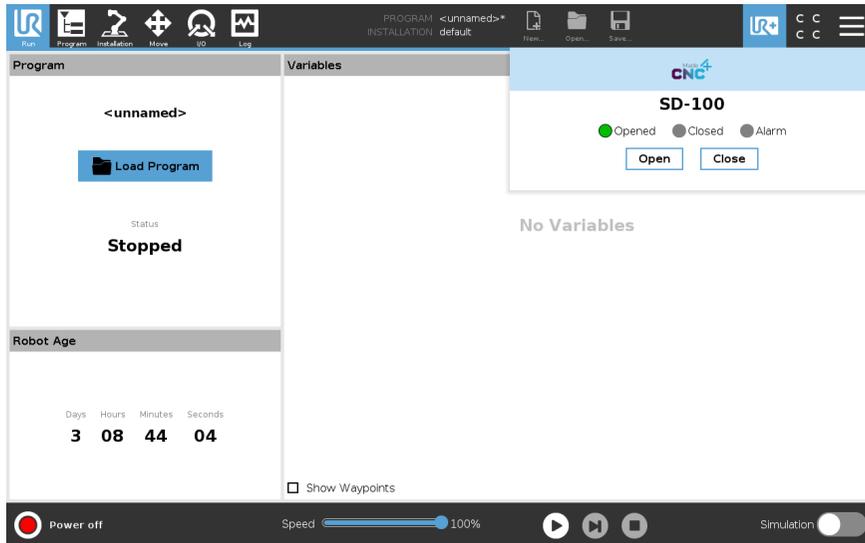
It is advised to verify the installation and settings, by using open- and close buttons on the toolbar (see *Toolbar* on page 29), before continuing. Verify that the indicators “Opened” and “Closed” light up when the door is in the respective positions.

The alarm signal can be tested by blocking the CNC door and attempting to close it, using the “Close” button. The Alarm signal must be cleared by pressing the “Config / Clear” on the controller board.

Toolbar

The toolbar provides an overview of the door state as well as access to controls. The controls should not be used while running a program but can be useful while programming the robot.

The toolbar can be accessed by pressing the “UR+” logo in the top-right corner of the screen:



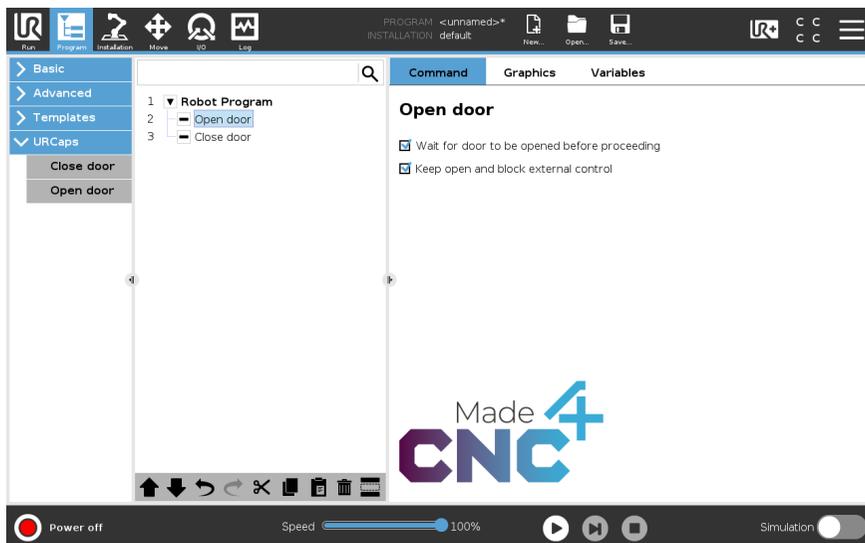
The toolbar is currently only available on Universal Robots eSeries robots.

Open Door node

This program node can be inserted into the program tree, and it will request the door to open. Per default, this node will block until the door is opened and the robot can safely enter the CNC machine.

The “*Open Door*” program node can be inserted in the “*Program*” panel, at the currently selected location in the program tree, by clicking “*URCaps*” → “*Open Door*” in the structure panel.

The program node will clear the “*Close Door*” signal and set the “*Open Door*” signal. It will wait for the “*Door Closed*” signal to be cleared by the Controller Board, indicating that the signal to open the door was properly received and the motion initiated, before continuing to the next program node.



When the check box “*Wait for door to be opened before proceeding*” is checked, the program will not continue beyond this program node before the door is fully opened and the input signal set as “*Door Opened*” in the installation screen is high.

When the check box “*Keep open and block external control*” is checked the program will continuously set the “*Open Door*” signal high, preventing external overrides of this signal. Only subsequent “*Close Door*” program node will remove this blockage and allow the door to close.

Close door node

This program node can be inserted into the program tree, and it will request the door to close.

The “Close Door” program node can be inserted in the “Program” panel, at the currently selected location in the program tree, by clicking “URCaps” → “Close Door” in the structure panel.

The program node will clear the “Open Door” signal and set the “Close Door” signal. It will wait for the “Door Open” signal to be cleared by the Controller Board, indicating that the signal to close the door was properly received and the motion initiated, before continuing to the next program node. The program node will also clear any external control blockage set by previous “Open Door” program nodes.



When the check box “Wait for door to be closed before proceeding” is checked the program will not continue beyond this program node before the door is fully closed and the Controller Board has set the “Door Closed” signal high.

Omron Components

The Safedoor Omron Components enable easy and reliable setup and operation, when using Safedoor in conjunction with an Omron Collaborative Robot. After the Safedoor system is installed and configured (see *Quick guide* on page 10), follow these steps to install and configure the components on an Omron Robot.

The Safedoor components are created using TMFLOW version 1.82.5100 and is compatible with TMFLOW version 1.76.3300 and above.

Installation

Before installing the Safedoor Components, the provided USB stick should be renamed to TMROBOT, before the Omron Robot will recognize it.

To do so, follow these steps:

1. Plug the USB into a PC
2. Find and right click on the USB in the file explorer
3. Press “Properties” in the drop-down menu
4. Find the property “name” and change it to: “TMROBOT”

If the Component ZIP is downloaded from the made4cnc.com website, and put onto a personal USB, do the previous steps to format it correctly, and continue to these steps:

5. Download the “Omron Component” zip file from made4cnc.com
6. Drag the zip file onto the respective USB
7. Right click the zip file and select “Extract Here”
8. Ensure that the extracted folder is named “TM_Export”

To install the Safedoor Components on an Omron Robot, start by inserting the prepared USB Stick in the Omron Robot. Then follow these steps:

1. “Menu” → “System” → “Import/Export”
2. Select device to be the inserted USB
3. Press the top left Import button
4. On the “Robot List”, select “Made4CNC”
5. Press Component
6. Select all 3 components with the prefix: “*Actuator_Made4CNC_Safedoor_*”
7. Press the Import button in the bottom right corner

The components are now installed on the Omron Robot. To activate the newly installed components: Navigate to “Settings” → “Components” and scroll to the bottom of the list. Select the 3 components, imported in the previous section. Finish by pressing the save button. The Safedoor Components are now ready to use.

Config Node

The *Config Node* imports and configures the global variables defining the I/O used by the *Open Door* and *Close Door* Nodes to interface with the *Safedoor Controller*. It also starts a non-pause thread, responsible for monitoring the error output from the Safedoor Controller

The *Config Node* can be inserted in the “*Flow program*” by dragging the “*Safedoor_Config*” icon from the “*Node Menu*” into the “*Flow Editing Area*”.

The *Config Node* needs to run once before any of the other Safedoor Components. The node should only be run once throughout a flow program. The node sets the I/Os used by the other Safedoor Nodes, *Safedoor_Open* and *Safedoor_Close*. When using the *Config Node*, the global I/O variables can be set through the edit component screen, in the SET_IO_VARIABLES method.



If these variables are not manipulated, they will keep their default values.

See table below for variable names and default values.

All variable names have the prefix: "g_Actuator_Made4CNC_Safedoor_".

| Name | Type | Description | Default Value |
|---------|----------|---|---------------|
| IO_J3_1 | Int | Store the input pin placement of the J3 pin 1 output: "Robot door opened" | 5 |
| IO_J3_2 | Int | Store the input pin placement for the J3 pin 2 output: "Robot door closed" | 6 |
| IO_J3_3 | Int | Store the input pin placement for the J3 pin 3 output: "Robot alarm" | 7 |
| IO_J1_1 | Int | Store the output pin placement for the J1 pin 1 Input: "Robot open door" | 6 |
| IO_J1_2 | Int | Store the output pin placement for the J1 pin 2 Input: "Robot close door" | 7 |
| Error | String[] | Stores an Error message if the Safedoor system outputs an error signal. | "" |

The variable names reference the I/O of the Safedoor Controller (See IO connections on page 17.) and should be configured to correspond to the desired I/O of the Omron Robot.

The *Config Node* creates a thread that monitors the error output of the *Safedoor Controller*. If this signal goes high, the program will stop, and store an error message in the global variable: *g_Actuator_Made4CNC_Safedoor_Error*.

Whenever the *Config Node* is run, the value of the error variable will be reset. Therefore, if the value of the variable is desired, it should always be read before activating the *Config Node* again.

Open Door Node

The *Open Door Node* serves the purpose of requesting the door to open. Per default, this node waits until it receives the “Door Opened” signal, before proceeding the flow. This allows the Robot to safely enter the CNC machine.

The *Open Door Node* can be inserted in the “Flow program” by dragging the “Safedoor_Open” icon from the “Node Menu” into the “Flow Editing Area”.

Important: The *Safedoor_Config* Node needs to have run **once** before the *Open Door Node* can function.

The node will set the variable “IO_J1_1” (Open Door) and clear the variable “IO_J1_2” (Close Door). The node will wait for the “Door Close” signal to be cleared by the Controller Board, indicating that the signal to open the door was properly received and the motion initiated, before continuing to the next program node.



Editing the node allows the user to determine if the program should wait until the door is opened, before proceeding the flow. In the edit menu, changing the default value of the boolean variable: “*Wait_Before_Proceed*”, will accomplish this. The variable determines whether the component will continue the program flow while opening the door, or if it will wait until it is fully open before continuing.

If the value is set to “*true*”, the node will wait till the door is fully opened before proceeding.

If the value is set to “*false*”, the flow will proceed directly after sending the “*Open Door*” signal.

Close Door Node

The *Close Door Node* serves the purpose of requesting the door to close. Per default, this node waits until it receives the “*Door Closed*” signal, before proceeding the flow. This allows the Robot to safely enter the CNC machine.

The *Close Door Node* can be inserted in the “*Flow program*” by dragging the “*Safedoor_Close*” icon from the “*Node Menu*” into the “*Flow Editing Area*”.

Important: The *Safedoor_Config* Node needs to have run **once** before the *Close Door Node* can function.

The node will set the variable “*IO_J1_2*” (Close Door) and clear the variable “*IO_J1_1*” (Open Door). The program node will wait for the “*Door Open*” signal to be cleared by the Controller Board, indicating that the signal to close the door was properly received and the motion initiated, before continuing to the next program node.



Editing the node allows the user to determine if the program should wait until the door is closed, before proceeding the flow. In the edit menu, changing the default value of the boolean variable: “*Wait_Before_Proceed*”, will accomplish this. The variable determines whether the component will continue the program flow while closing the door, or if it will wait until it is fully closed before continuing.

If the value is set to “true”, the node will wait till the door is fully closed before proceeding.

If the value is set to “false”, the flow will proceed directly after sending the “*Close Door*” signal.

6 Safety

System integrator responsibilities

The system integrator is responsible for ensuring that the applicable safety laws and regulations in the country where the product is incorporated are followed and that all significant hazards in the complete automated system are eliminated. This includes, but is not limited to:

- Performing a risk assessment for the complete system, including CNC machine and/or robot
- Interfacing other machinery and additional safety devices, if defined according to the risk assessment
- Setting up the appropriate safety settings in the robot- and CNC software and other relevant safety controllers
- Ensuring that the user will not modify any safety measures
- Validating that the total system is working correctly and according to system requirements
- Writing instructions for use (To be read by daily operators etc.)
- Marking the installation with the relevant signs and contact information system integrator
- Collection all documentation in a technical file; including the risk assessment and this manual

Intended use

The Safedoor system is intended to be installed on a CNC machine to automatically open and close one or two sliding doors of the CNC machine. The CNC machine must have mechanical stops at both ends of the door(s) linear travel and it must provide a safe locking mechanism, ensuring that the door cannot be opened while the CNC machine is operating.

The door can be opened to 1000mm and weight up to 400kg. Opening speed is maximum 500mm/s and will stop when meeting certain resistance. The Safedoor Actuators and Controller should only be used under conditions specified in the *Technical Sheet* on page 4.

The Safedoor Controller is installed with electrical 24V signals between controller and CNC machine and/or robot. The wiring must be carried out by qualified personnel, e.g. an electrician qualified to install wires in CNC machines and robots. When connecting to external machinery, such as CNC machines, robots and other industrial- and automation equipment, only signals intended for external communication. Note that some CNC machines have dedicated communication ports, specific digital I/Os, etc., designated for incorporation with an automated door function.

Any use of the Safedoor system deviating from the intended use is deemed to be impermissible misuse. This includes, but is not limited to:

- Use in potentially explosive atmospheres
- Use in non-industrial environments

- Use before conducting risk assessment
- Use where risk of clamping a human's head and/or neck is significant
- Use outside permissible operational conditions and specifications
- Use where the door(s) presents a cutting and/or impact risk
- Use where safety features of the CNC machine door(s) are bypassed or compromised
- Use as climbing or lifting aid
- Use where the actuator is constantly soaked in oil or other liquids

All operators must be trained in correct use of the equipment, including all relevant safety precautions.

Risk assessment

The system integrator must perform a risk assessment on the complete CNC machine and/or robot application. The Safedoor Controller and Actuators is only components in an automation application and the safe use of the Safedoor system rely on the integrators ability to design a safe application.

The Safedoor system is designed with these risk reduction features:

- Three different speed settings, allowing the integrator to reduce the travel speed if required by the risk assessment. The lower travel speed, the lower impact from the inertia (weight) of the door.
- Force limiting, reducing pinch and crushing hazards.
- Non-backdrivable gear, ensuring the door does not move unintended.

The safety of the overall automated system depends on the design and shape of individual CNC machine doors. The integrator of the Safedoor system must consider if the CNC machine doors are suitable for automatic operation, and if needed according to the integrators risk assessment edges of the door must be upgraded with soft padding or the edges must be smoothed to have suitable contact surfaces. All changes to the CNC machine itself must be done in according to guidelines and requirements for such CNC machine.

The weight (inertia) of the CNC door and thereby potential impact with such door must be considered in the risk assessment. Light doors with large and flat closing surfaces poses less risk than heavy doors with thin/smaller closing surfaces. The integrator must also consider how the Safedoor Actuator is mounted and ensure that the mounting itself do not create any additional risks, e.g. risk of clamping.

In applications where the Safedoor system is used together with a robot, the integrator must consider if a potential collision between the door(s) and robot can create any additional hazards and mitigate any risk from such hazards as required by the risk assessment.

It is the responsibility of the integrator to conduct a risk assessment of the final installation, including the Safedoor system, the CNC machine and any other

equipment used. All hazards as well as the severity of these must be identified and assessed before placing the installation into service.

Below is a list of the potential hazards that Made4CNC has identified as significant and that must be considered by the integrator:

- Collision between moving parts and human body parts (e.g. head and neck)
- Clamping between moving parts and robot or other equipment (e.g. head and neck)
- Consequences due to improper mounting and/or loosening of bolts/screws
- Consequences due to lack of maintenance
- Contact between door(s) and robotics equipment and/or workpiece

Maintenance and safety checks must be performed with appropriate and regular intervals, and at least once time per year. The integrator must define such appropriate intervals to the user and/or operator, e.g. in the information for use.

It is recommended that national standards and guidelines are observed in the design phase of the complete installation, and that the principles for risk assessment defined in ISO 12100 are followed.

It is recommended that installations as a whole are connected with shared emergency stop functionality, so that a push of any emergency stop button stops motion of all machines in the reasonable proximity, as determined by the risk assessment.

It must be considered if a shared Lockout-Tagout function is required, where all mains power (230V/110V) to all parts of the installation can be disconnected at the same time (E.g the CNC machine, the robot and the Safedoor system all together). It is recommended to follow ISO 14118.

Exerted force

The table below shows the typical actuator force at different levels of door openings. The data is based on tests carried out by third party test facility (Force Technology) and can be used as guidelines when performing risk assessment.

| Opening [mm] | Force [N] |
|---------------------|------------------|
| 15 | 108 |
| 40 | 124 |
| 80 | 170 |
| 120 | 299 |
| 150 | 383 |

If it is found by risk assessment that the combination of physical properties of the CNC door and moving parts of Safedoor actuator and/or a robot results in risks that cannot be sufficiently reduced with safety features provided by Safedoor System and/or the robot then additional risk reduction measures must be added. Such measures could include protective devices such as laser scanners or light curtains in combination with mechanical shielding.



Environmental safety

The Safedoor system, including Actuators and Controllers, and any other Made4CNC product must be decommissioned and disposed in accordance with applicable national laws, regulations and standards.

The product is manufactured with restricted use of hazardous substances to protect environment and operators, as defined by the EU “RoHS” Directive 2001/65/EU. The restrictions include lead, cadmium, mercury, chromium VI, polybrominated biphenyls and polybrominated diphenyl ethers.

National requirements apply to importers according to EU “WEEE” Directive 2012/19/EU. Follow this link for more information.

<https://www.ewrn.org/national-registers/national-registers>



General safety instructions

Generally, all laws, regulations and legislations of the country of installation and use must be complied with. Observe all guidelines in this manual and the warnings below:



DANGER

All wiring and connections must be performed by personal qualified to work with mains voltage (230V/110V). Electrical shock can result in death.

Do not touch any electrical components inside the controller besides the dedicated buttons.

Do not take the internal power supply apart. It operates with internal voltages up to 500V, and voltage can be present for up to 24 hours after disconnection.

Do not use the product if any electrical or mechanical components are damaged or modified. Made4CNC disclaims any and all liability if the product is modified in any way. Made4CNC cannot be held responsible for any damages caused to the product or any other equipment due to programming errors or malfunction of the Safedoor product.

Do not modify any safety features of the CNC door(s). The CNC machine must be prevented from operating when the door is open. CNC machine operation with open door(s) can result in death or serious injury.

7 Warranties

Product warranty

Without prejudice to any claims the customer (user) may have in relation to the dealer or retailer, the customer shall be granted a manufacturer's warranty under the conditions set out below:

In the case of new devices and their components exhibiting defects resulting from manufacturing and/or material faults within 12 months of entering into services (maximum 15 month after shipment), Made4CNC shall provide the necessary spare parts, while the customer shall provide the working hours to replace the spare parts, either replace the failed part with another part in similar state of wear and tear or repair said failed part.

This warranty shall be invalid if the defect is attributable to improper treatment and/or failure to comply with information contained in the user guides. This warranty shall not apply to or extend to service performed by an authorized dealer or the customer themselves (including installation, software downloads and configuration). Purchase documentation, together with the date of purchase, shall be required as evidence for invoking the warranty. Claims under this warranty must be submitted within one month of the defect becoming evident. Ownership of products, devices, components and spare parts replaced by and returned to Made4CNC shall vest in Made4CNC. Any other claims resulting out of or in connection with the product shall be excluded from this warranty. Nothing in this warranty shall attempt to limit or exclude a customer's statutory rights nor the manufacturer's liability for death or personal injury resulting from its negligence. Insofar as no warranty default exists, Made4CNC reserves the right to charge the customer for the replacement or repair. The above provision does not imply change in the burden of proof to the detriment of the customers. In case of a device exhibiting defects, Made4CNC shall not be liable for any incidental, special, indirect or consequential damages, including but not limited to, loss of profit, loss of use, loss of production or damages to other equipment.

Disclaimer

Made4CNC continues to improve the reliability and performance of its products, and therefore reserve the right to upgrade the product without any prior notice. Made4CNC takes thorough care that the content of this manual is precise and correct but takes no responsibility of any erroneous or missing information.

8 Certifications

Declarations, certificates and standards are listed in this section.

Applied standards

Standards used under the development of the product is listed in this section. EU Directive numbers noted in square brackets indicates that the standard is harmonized under that directive.

ISO 12100:2010

EN ISO 12100:2010 (E) [2006/42/EC]

Safety of machinery – General principles of design – Risk assessment and risk reduction

The product is evaluated in accordance with the principles of these standards.

IEC 60529:2013

EN 60529/A2:2013

Degrees of protection provided by enclosures (IP Code)

This standard defines enclosure ratings regarding protection against dust and water. The actuator and the controller are designed with an IP classification according to this standard. See stickers on the controller cabinet and actuator.

IEC 61131-2:2017

EN 61131-2:2017 [Pending harmonization 2014/30/EU]

Programmable controllers

24 V I/O signals from/to the controller are designed for reliable communication with robots, CNC machines and PLCs conforming to this standard.

ISO 13732-1:2007

EN ISO 13732-1:2008 [2006/42/EC]

Ergonomics of the thermal environment. Methods for the assessment of human responses to contact with surfaces.

Part 1: Hot surfaces

The product is designed so that the surface temperature of the product is kept under the ergonomic limits defined by this standard.

IEC 61000-6-2:2016

IEC 61000-6-4:2018

EN 61000-6-2:2019 [Pending harmonization 2014/30/EU]

EN 61000-6-4:2019 [Pending harmonization 2014/30/EU]

Electromagnetic compatibility (EMC)

Part 6-2: Generic standards – Immunity for industrial environments

Part 6-4: Generic standards – Emission standard for industrial environments

The product is evaluated according to the limits and principles in these standards.

IEC 60068-2-1:2007
IEC 60068-2-2:2007
IEC 60068-2-27:2008
IEC 60068-2-64:2008
EN 60068-2-1:2007
EN 60068-2-2:2007
EN 60068-2-27:2009
EN 60068-2-64:2008

Environmental testing

Part 2-1: Tests – Test A: Cold

Part 2-2: Tests – Test B: Dry heat

Part 2-27: Tests – Test Ea and guidance: Shock

Part 2-64: tests -Test Fh: Vibration broadband random and guidance

The product is designed and prepared to pass tests defined in these standards.

IEC 60664-1:2020

EN 60664-1:2020 [2014/35/EU]

Insulation coordination for equipment within low-voltage supply systems

Part 1: Principles, requirements and tests

This standard is observed during development of the electrical circuits inside the product.

ISO 10218-2:2011

EN ISO 10218-2:2011 [2006/42/EC]

ANSI/RIA R15.06

CAN/CSA-Z434-14

Robots and robotic devices – Safety requirements for industrial robots

Part 2: Robot systems and integration

This standard is relevant for robotic applications and should be observed by integrators when integrating this product in conjunction with one or more robots. The product evaluated and prepared for integrations according to these standards.

ISO/TS 15066:2016

RIA TR R15.606

Robots and robotic devices — Collaborative robots

This technical specification is relevant for collaborative robot applications and should be observed by integrators when integrating this product in conjunction with one or more cobots. The product evaluated and prepared for integrations according to the normative requirements in this technical specification.

CE/EU Declaration of incorporation (Original)

According to European Machinery Directive 2006/42/EC annex II 1.B.

The manufacturer:

Made4CNC ApS
Helgavej 26
DK-5230 Odense M
DENMARK
www.made4cnc.com

declares that the product:

| | |
|---------------------|--------------------------------|
| Types: | SD000 to SD999 with controller |
| Model: | Safedoor |
| Generation: | 1 |
| Serial, controller: | SDC1-000597 to SDC1-999999 |
| Serial, actuator: | SDA1-000000 to SDA1-999999 |

configured with one controller and one or two actuators is partly completed machinery according to 2006/42/EC and may not be put into service before the machinery in which it will be incorporated is declared in conformity with the provision of Directive 2006/42/EC and with the regulations transposing it into national law.

The product is prepared for compliance with essential requirements of Directive 2006/42/EC under correct incorporation conditions; follow instructions and guidance in this manual. Compliance with all essential requirements of Directive 2006/42/EC relies on a final risk assessment that also takes CNC machine, robot and other equipment into account.

Technical documentation is prepared according to Directive 2006/42/EC annex VII part B and is available in electronic form to national authorities upon legitimate request. Undersigned is based on the manufacturer's address and authorized to compile this documentation.

Additionally, the product declares in compliance with the following directives, according to which the product is CE marked:

- 2014/30/EU – Electromagnetic Compatibility Directive (EMC)
- 2011/65/EU – Restriction of the use of hazardous substances (RoHS)

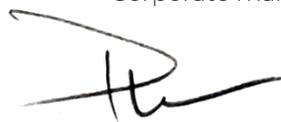
Relevant essential health and safety requirements of the following EU directives are also applied:

- 2014/35/EU – Low Voltage Directive (LVD)
- 2012/19/EU – Waste of Electrical and Electronic Equipment (WEEE)

A list of applied standards is provided in this manual.

Odense, January 19th, 2022

Corporate management



Peter Nadolny Madsen
Chief Executive Officer

The Safedoor system is an innovative and safe solution to enable robotized tending of existing CNC machines.

The Actuator is specially designed for the purpose, allowing fast, continuous operation of CNC machine doors. The intelligent Controller monitors that all aspects of the doors motion are smooth and reliable.

The built-in safety features allow safe human / machine collaboration without the need to safety fencing. This makes the Safedoor system ideal for collaborative robot applications.